Reversing Transitions in Bounded Petri Nets*

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Abstract. Reversible computation deals with mechanisms for undoing the effects of actions executed by a dynamic system. This paper is concerned with reversibility in the context of Petri nets which are a general formal model of concurrent systems. A key construction we investigate amounts to adding 'reverse' versions of selected net transitions. Such a static modification can severely impact on the behaviour of the system, e.g., the problem of establishing whether the modified net has the same states as the original one is undecidable. We therefore concentrate on nets with finite state spaces and show, in particular, that every transition in such nets can be reversed using a suitable set of new transitions.

Keywords: Petri net, reversibility, reversible computation

1 Introduction

Reversible computation deals with (typically local) mechanisms for undoing the effects of actions executed by a dynamic system. Such an approach has been applied, in particular, to various kinds of process calculi and event structures (see, e.g., [3–6, 8, 11, 12, 10]), and to a category theory based setting [7].

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This paper is concerned with reversibility in the context of Petri nets which are a general formal model of concurrent systems. A key construction we investigate amounts to adding 'reverse' versions of selected net transitions, e.g., a 'straightforward' reverse simply changes the directions of arcs adjacent to a transition being reversed. As shown in [2], such a static modification can severely impact on the behaviour of the system, e.g., the problem of establishing whether the modified net has the same states as the original one is undecidable.

We therefore concentrate in this paper on Petri nets with finite state spaces, more precisely bounded Place/Transition-nets (PT-nets). The state spaces of such nets can be represented by finite labelled transition systems (flts's) which are a convenient tool for specifying different variants of reversibility. One can therefore aim at synthesising a PT-net with 'reversed' behaviour given by an flts.

In this paper we show that it is, in general, impossible to reverse a transition using its straightforward reverse. What is more, the situation does not change if we relax the notion of a reverse by only requiring that the effect of its execution is opposite to that of the original transition. We therefore relax the requirement further, by allowing several reverses for a single transition. This leads to our main result that every transition in a bounded PT-net can be reversed using a suitable set of new transitions.

2 Preliminaries

Transition systems

A finite labelled transition system (or, simply, flts) is a tuple $TS = (S, T, \rightarrow, s_0)$ with a finite set of states S, a finite set of labels T, a finite set of $arcs \rightarrow \subseteq (S \times T \times S)$, and an *initial state* $s_0 \in S$.⁴ A label t is fireable at $s \in S$, denoted by $s[t\rangle$, if $(s, t, s') \in \rightarrow$, for some $s' \in S$. A state s' is reachable from s through the execution of $\sigma \in T^*$, denoted by $s[\sigma\rangle s'$, if there is a directed path from s to s' whose arcs are labelled consecutively by σ . The set of states reachable from sis denoted by $[s\rangle$. A sequence $\sigma \in T^*$ is fireable, from a state s, denoted by $s[\sigma\rangle$, if there is some state s' such that $s[\sigma\rangle s'$.

Let $t_{TS}^{\bullet} = \{s \in S \mid (s',t,s) \in \rightarrow$, for some $s' \in S\}$ and $t_{TS}^{\bullet} = \{s \in S \mid (s,t,s') \in \rightarrow$, for some $s' \in S\}$ be respectively the sets of all states having an incoming arc labeled with t, and an outgoing arc labeled with t. The set of all arcs labelled by t is denoted by t. We assume that each t is nonempty.

Two fits's, $TS_1 = (S_1, T, \rightarrow_1, s_{0_1})$ and $TS_2 = (S_2, T, \rightarrow_2, s_{0_2})$, are *isomorphic* if there is a bijection $\zeta \colon S_1 \to S_2$ with $\zeta(s_{0_1}) = s_{0_2}$ and $(s, t, s') \in \rightarrow_1 \Leftrightarrow (\zeta(s), t, \zeta(s')) \in \rightarrow_2$, for all $s, s' \in S_1$.

Petri nets

A Place/Transition Petri net (or, simply, net) is a tuple $N = (P, T, F, M_0)$,

⁴ An fits may be considered as a finite automaton with no accepting states.

where P is a finite set of places, T is a finite set of transitions (or actions), F is the flow function $F: ((P \times T) \cup (T \times P)) \to \mathbb{N}$ specifying the arc weights, and M_0 is the initial marking (where a marking is a mapping $M: P \to \mathbb{N}$, indicating the number of tokens in each place). A transition $t \in T$ is enabled at a marking M, denoted by $M[t\rangle$, if $M(p) \ge F(p, t)$, for all $p \in P$. The effect of a transition ton a place p is $eff_p(t) = F(t, p) - F(p, t)$. The firing of t at marking M leads to M', denoted by $M[t\rangle M'$, if $M[t\rangle$ and $M'(p) = M(p) + eff_p(t)$ for every $p \in P$.

The notions of enabledness and firing, $M[\sigma\rangle$ and $M[\sigma\rangle M'$, are extended in the usual way to sequences $\sigma \in T^*$, and $[M\rangle$ denotes the set of all markings reachable from M. We assume that each transition is enabled in at least one reachable marking. There is a partial order relation < on the markings of a Petri net defined so that $M \leq M'$ if $M(p) \leq M'(p)$, for every place $p \in P$. It is easy to observe that transition enabledness is *monotonic*, which means that if a transition t is enabled at a marking M and $M \leq M'$, then t is also enabled at M'.

A Petri net $N = (P, T, F, M_0)$ net is bounded if $[M_0\rangle$ is finite, and its reachability graph is then defined as an fits

$$RG(N) = ([M_0\rangle, T, \{(M, t, M') \mid M, M' \in [M_0\rangle \land M[t\rangle M'\}, M_0)$$

If a labelled transition system TS is isomorphic to the reachability graph of a Petri net N, then we say that N solves TS, and TS is synthesisable to N.

Definition 1 (transition reverse). A (strict) reverse of a transition $t \in T$ in a net $N = (P, T, F, M_0)$ is a new transition \underline{t} such that $F(p, \underline{t}) = F(t, p)$ and $F(\underline{t}, p) = F(p, t)$. An effect-reverse of a transition $t \in T$ is a new transition \overline{t} such that eff $_p(\overline{t}) = -eff_p(t)$, for all places $p \in P$.

To improve readability, we depict newly created reverses and adjacent arcs by dashed (or dotted) lines. Clearly, for a given transition t, its strict reverse \underline{t} is unique and, at the same time, it is an effect-reverse of t. However, an effect-reverse \overline{t} is not necessarily a strict reverse (see Figure 1).

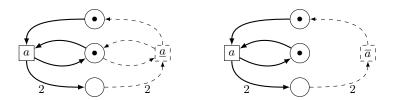


Fig. 1. A transition a and its (strict) reverse \underline{a} (lhs), and an effect-reverse \overline{a} , which is not a strict reverse (rhs).

(Un)solvable words

A word $w = t_1 t_2 \dots t_n$ of length $n \in \mathbb{N}$ uniquely corresponds to a labelled transition system $TS(w) = (\{0, \dots, n\}, T, \{(i-1, t_i, i) \mid 0 < i \le n \land t_i \in T\}, 0).$

We say that a net N solves a word w if it solves TS(w). A word w is then called *solvable*, and otherwise *unsolvable*.

If a word w is solvable, then so are all its factors (where a *factor* w' satisfies w = vw'u, for some v and u). Thus, the unsolvability of any proper factor of w entails the unsolvability of w. For this reason, the notion of a *minimal unsolvable word*, defined as an unsolvable word with all proper factors being solvable, is well-defined (see [1] for details).

The mirror image w^R of a word w is w written from right to left.

3 Solvability of flts's with reverses

We now define reverses for labelled transition systems, and investigate how they affect the solvability of the resulting flts's. We first introduce the notions of reduction and extension of an flts.

Definition 2 (fits reduction and extension). Let $TS = (S, T, \rightarrow, s_0)$ be a solvable fits.

- The reduction of TS by deleting $t \in T$ is an flts $TS^{[-t]} = (S', T \setminus \{t\}, \rightarrow', s_0)$ such that:
 - $S' \subseteq S$ are all the states reachable in TS without using \overrightarrow{t} ;
 - $(s_1, a, s_2) \in \to'$ if $(s_1, a, s_2) \in \to$, for all $a \neq t$ and $s_1, s_2 \in S'$.
- The extension of TS by reversing $t \in T$ is an fits $TS^{[+\bar{t}]} = (S, T \cup \{\bar{t}\}, \rightarrow', s_0)$ such that, for all $s_1, s_2 \in S$:
 - $(s_1, a, s_2) \in \to'$ if $(s_1, a, s_2) \in \to$, for all $a \in T$;
 - $(s_1, \overline{t}, s_2) \in \to'$ if $(s_2, t, s_1) \in \to$.

These above notions can be extended to finite sets of transitions, by setting $TS^{[-t_1,t_2...t_n]} = TS^{[-t_1][-t_2]...[-t_n]}$ and $TS^{[+\overline{t_1,t_2...t_n}]} = TS^{[+\overline{t_1}][+\overline{t_2}]...[+\overline{t_n}]}$.

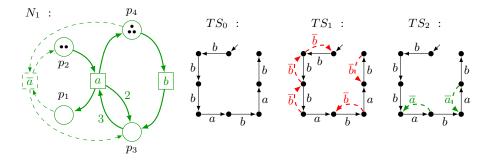


Fig. 2. TS_0 and $TS_2 = TS_0^{[+\bar{a}]}$ are solvable by net N_1 (respectively without and with the dashed part), while $TS_1 = TS_0^{[+\bar{b}]}$ is unsolvable.

Consider a word w = bbbabab which, in Figure 2, corresponds to a solvable fits TS_0 . If we add a reverse of transition a, we obtain TS_2 which is solvable by N_1 . We will later show that reversing transition b leads to an unsolvable fits TS_1 .

The \overline{a} in Figure 2 is an effect-reverse but not a strict reverse of a. We will now show that if a label a can be effect-reversed, i.e., $TS^{[+\overline{a}]}$ is solvable, then there exists a solution in which transition \overline{a} is a strict reverse of a.

Proposition 1. Let $TS = (S, T, \rightarrow, s_0)$ be a solvable fits and $a \in T$. If $TS^{[+\overline{a}]}$ is solvable then there exists its solution such that \overline{a} is a strict reverse of a.

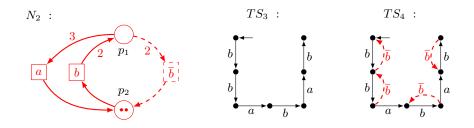


Fig. 3. Adding a reverse \overline{b} in $TS_4 = TS_3^{[+\overline{b}]}$ does not violate solvability.

Consider N_2 of Figure 3 without the dashed part. It solves the word *bbabab*, and so its reachability graph is isomorphic to TS_3 . Unlike the case with the reverse of b in TS_1 , TS_4 obtained from TS_3 by adding a reverse for transition b is solvable by N_2 with dashed part. Note that, in N_2 , \overline{b} is a strict reverse of b. Similarly, we may reverse a in TS_3 , obtaining TS_5 of Figure 4. This flts is solvable by the net N_3 with the dashed part.

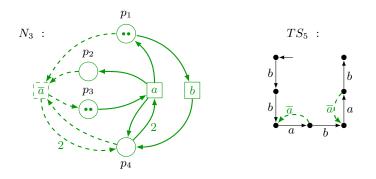


Fig. 4. $TS_5 = TS_3^{[+\overline{a}]}$ is solvable (e.g. by N_3).

The next result states that for a given fits and two of its transitions, if adding a reverse for each of them separately yields solvable fits's, then the fits with both reverses is also solvable.

Proposition 2. Let $TS = (S, T, \rightarrow, s_0)$ be a solvable fits and $a \neq b \in T$. If both $TS^{[+\overline{a}]}$ and $TS^{[+\overline{b}]}$ are solvable, then so is $TS^{[+\overline{a},\overline{b}]}$.

For $TS = TS_3$ of Figure 3, by Proposition 2, starting from the solutions for $TS_4 = TS^{[+\overline{a}]}$ and $TS_5 = TS^{[+\overline{b}]}$, we can construct a solution N_4 for $TS_6 = TS^{[+\overline{a},\overline{b}]}$ depicted in Figure 5.

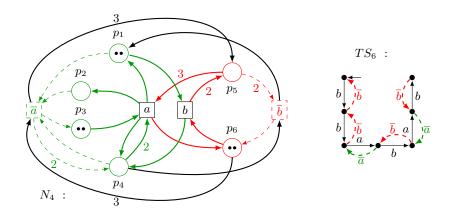


Fig. 5. N_4 solving $TS_6 = TS_3^{[+\overline{a,b}]}$ derived by synchronising the transitions of N_2 and N_3 .

We end this section looking at the solvability of words over a two-letter alphabet.

Proposition 3. Let $w \in \{a, b\}^*$ be a minimal unsolvable word. Then $TS(w^R)$ is solvable.

Due to Propositions 2 and 3, reversing of both transitions in the mirror image w^R of some minimal unsolvable word w over $\{a, b\}$ yields solvability of w, which is a contradiction. Hence, the following corollary holds

Corollary 1. Let $w \in \{a, b\}^*$ be a minimal unsolvable word and $TS = TS(w^R)$. Then $TS^{[+\overline{a}]}$ or $TS^{[+\overline{b}]}$ is unsolvable.

The above result explains why b in TS_1 of Figure 2 cannot be reversed. All we need to observe is that w = bbbabab is the mirror image of a minimal unsolvable word bababbb, and then recall that a can be reversed in TS_1 .

4 Splitting reverses

In this section we discuss the possibility of "splitting" reverses. More specifically, we investigate flts's in which more than one reverse to a given transition can exist.

Consider N_5 of Figure 6, together with its reachability graph TS_7 . First, we observe that $eff_{\bar{b}_1}(p) = eff_{\bar{b}_2}(p) = -eff_b(p)$, for every place p. Hence, transitions \bar{b}_1 and \bar{b}_2 are both effect-reverses for b. We have already seen that it is impossible to synthesise an flts with just one reverse of b (i.e., TS_1 of Figure 2), but the behaviour of N_5 is exactly what one might indeed want to obtain. The only difference is that N_5 has more than one reverse for b. In what follows, we show that every action of a bounded net can be reversed using finitely many effect-reverses.

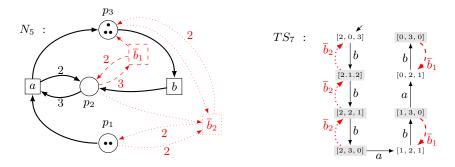


Fig. 6. Splitting reverses in TS_7 results in solvability.

Definition 3 (splitting reverse). Let $TS = (S, T, \rightarrow, s_0)$ be a solvable fits. The extension of TS by a set \overline{T} of reverses of $t \in T$ is an fits $TS^{[+t\phi]} = (S, T', \rightarrow', s_0)$ such that:

- $-\phi: \overrightarrow{t} \to 2^{\overline{T}} \setminus \{\emptyset\}$ is a mapping specifying all possible ways in which each of *t*-labelled arcs can be reversed;
- $-T' = T \cup \overline{T};$ - $(s_1, a, s_2) \in \to' \text{ if } (s_1, a, s_2) \in \to, \text{ for any } a \in T;$ - $(s_1, t', s_2) \in \to' \text{ if } (s_2, t, s_1) \in \to \text{ and } t' \in \phi((s_1, t, s_2)).$

We also extend the above notion in the usual way to $TS^{[+t_1\phi_1,t_2\phi_2,...,t_n\phi_n]}$.

Lemma 1. Let $N = (P, T, F, M_0)$ be a bounded net, $TS = ([M_0\rangle, T, \rightarrow, M_0)$ be its reachability graph, and $t \notin T$ be a new transition symbol. If a reachable marking M is \leq -maximal in $[M_0\rangle$ and $M' \in [M_0\rangle$, then

$$TS' = ([M_0\rangle, T \cup \{t\}, \to \cup \{(M, t, M')\}, M_0)$$

is a solvable flts.

Proof. Let $N' = (P, T \cup \{t\}, F', M_0)$, where:

$$\begin{aligned} F'(p,a) &= F(p,a) \quad \text{for all } p \in P \text{ and } a \in T \\ F'(a,p) &= F(a,p) \quad \text{for all } p \in P \text{ and } a \in T \\ F'(p,t) &= M(p) \quad \text{for every } p \in P \\ F'(t,p) &= M'(p) \quad \text{for every } p \in P. \end{aligned}$$

We then obtain that:

- (1) t is not enabled at any marking $M'' \neq M$ reachable in N. Indeed, suppose that there exists such a marking M''. Then, by the definition of enabledness, $M''(p) \geq F'(p,t) = M(p)$, for every $p \in P$. Hence $M'' \geq M$, which contradicts the \leq -maximality of M.
- (2) $M[t\rangle M'$. This follows directly from the definition of F'.

We then observe that, by (1) and (2), the sets of reachable markings of the nets N and N' are equal, and RG(N') = TS'.

Lemma 1 states that to a given solvable fits (with a solution $N = (P, T, F, M_0)$) one can always add a new edge $(s, t_{(s,s')}, s')$, obtaining another solvable fits, provided that s is a state corresponding to some marking M, which is \leq -maximal in $[M_0\rangle$, and $t_{(s,s')}$ denotes the label of the edge from s to s', such that $t_{(s,s')} \notin T$. We will use this fact to prove the following theorem

Theorem 1. Let $TS = (S, T, \rightarrow, s_0)$ be a solvable fits. Then, for every $t \in T$, there exists a finite set \overline{T} and a function $\phi : \overrightarrow{t} \rightarrow 2^{\overline{T}} \setminus \{\emptyset\}$ such that $TS^{[+t\phi]}$ is solvable.

Proof. Let $N = (P, T, F, M_0)$ be a net solving TS. As TS is finite, N is bounded, and so we can calculate a common bound n on the tokens in the reachable markings for all the places, $n = \max(M(p) \mid M \in [M_0), p \in P)$.

We extend N to $N' = (P \cup P', T, F', M'_0)$ by adding complement places [9] $P' = \{p' \mid p \in P\}$ in such a way that, for all $M \in [M_0\rangle$ and $p \in P$, we define M', such that M'(p) = M(p) and M'(p') = n - M(p). This can be done by inserting in the initial marking $n - M_0(p)$ tokens into each $p' \in P'$, and setting F'(p', a) = F(a, p) as well as F'(a, p') = F(p, a), for all $p' \in P'$ and $a \in T$.

Since, for distict markings $M_1, M_2 \in [M'_0\rangle$, there exists a place $p \in P$ (in which they differ) such that $M_1(p) > M_2(p)$ and $M_1(p') < M_2(p')$, or $M_2(p) > M_1(p)$ and $M_2(p') < M_1(p')$, all distinct markings reachable in N' are \leq -incomparable. Hence all markings reachable in N' are \leq -maximal in $[M'_0\rangle$. By the construction, the reachability graph of N' is isomorphic to TS.

We then construct TS' by adding to TS a set \overline{T} of $|\overrightarrow{t}|$ new transitions in such a way that, for every $(p, t, q) \in \rightarrow$, we also add $(q, t_{(q,p)}, p) \in \rightarrow$. We then define a function $\phi : \overrightarrow{t} \rightarrow 2^{\overline{T}} \setminus \{\emptyset\}$ in such a way that $\phi((p, t, q)) = \{t_{(q,p)}\}$.

Finally, by repeatedly using Lemma 1 for the net N', we obtain that $TS' = TS^{[+t\phi]}$ is solvable.

The construction described in the proof of Theorem 1 will in most cases lead to a substantial enlargement of the net, as the size of places is doubled, and the number of newly created transitions is bounded by the size of the reachability graph of the initial net. However, as illustrated by the example depicted in Figure 6, there may also exist solutions that are much smaller. Hence, there is a room for improvement of the suggested constructive technique.

5 Infeasibility for reversing

To draw attention to another important issue, which becomes relevant during the analysis of fits's from the viewpoint of reversibility of transitions, let us consider the following example.

Suppose that one attempted to introduce a reverse for a in TS_8 of Figure 7, which can be solved by N_6 . Although there exists a (strict) reverse \overline{a} in N_6 , depicted in Figure 7, the meaning of \overline{a} may be confusing. We cannot regard it as an undoing of the executing of action a, since N_6 can fire $bc\overline{a}$ where a does not occur at all. What is more, we can keep repeating the firing of $bc\overline{a}$ indefinitely, without executing a even once. To address this situation, we introduce the notion of infeasibility for reversing.

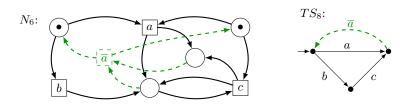


Fig. 7. $TS^{[+\overline{a}]}$ allows execution of \overline{a} without executing of a.

Definition 4. Let $TS = (S, T, \rightarrow, s_0)$ be an flts. Then $a \in T$ is infeasible (for reversing), if $TS^{[+\overline{a}]}$ has a path starting from s_0 with more occurrences of \overline{a} than a. Otherwise, a is feasible (for reversing).

There is a straightforward necessary condition for being feasible for reversing.

Proposition 4. Let $TS = (S, T, \rightarrow, s_0)$ be an flts and $t \in T$. If $TS^{[-t]}$ has a path from $\bullet_{TS} \cup \{s_0\}$ to t_{TS}^{\bullet} then t is infeasible for reversing.

In general, the reversed implication does not hold. Take, for example, $TS_{10} = TS_{9}^{[+\overline{a}]}$ of Figure 8. It has a path labelled $acd\overline{aa}$, with more \overline{a} 's than a's, implying

the infeasibility for reversing of transition a in TS_9 . However, the reduction of TS_9 by deleting a, namely $TS_9^{[-a]}$ has no path starting from $\bullet a_{TS_9} \cup \{s_0\}$ to a_{TS}^{\bullet} . Note that TS_{10} and TS_9 are both solvable (see N_7 of Figure 8 with or without dashed arcs, respectively). We will now show that one can always

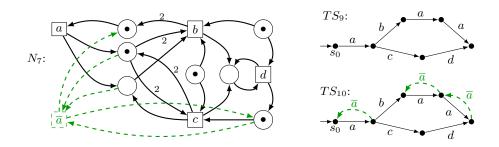


Fig. 8. *a* is infeasible for reversing in TS_9 , even though $TS_9^{[-a]}$ has no path from ${}^{\bullet}a_{TS_9} \cup \{s_0\}$ to $a_{TS_9}^{\bullet}$.

establish whether a label of an flts is (in)feasible for reversing. To this end, formulate the following decision problem:

Feasibility for Reversing Problem Instance: An flts $TS = (S, T, \rightarrow, s_0)$ and $t \in T$. Question: Is t feasible for reversing in TS?

Proposition 5. The Feasibility for Reversing Problem is decidable.

Proof (Sketch of the algorithm.).

The following algorithm reduces the problem of checking the feasibility of a transition for reversing to the problem of finding shortest paths in a weighted digraph.

Input: An fits $TS = (S, T, \rightarrow, s_0)$ and $t \in T$. **Output:** YES if t is feasible for reversing in TS; otherwise NO.

Procedure:

1. Compute a weighted graph G = (V, E, w) on the basis of the extension $TS^{[+\bar{t}]} = (S, T \cup \{\bar{t}\}, \rightarrow', s_0)$ of TS, in the following way (for all $s, s' \in S$, $a \in T \cup \{\bar{t}\}$): -V = S; $-(s, s') \in E$ if $(s, a, s') \in \rightarrow'$; $-w((s, s')) = \begin{cases} 1 & \text{if } (s, t, s') \in \rightarrow' \\ -1 & \text{if } (s, \bar{t}, s') \in \rightarrow' \\ 0 & \text{otherwise.} \end{cases}$

- 2. Use, e.g., Bellman-Ford algorithm, to search for a state s_{wit} , such that the distance between s_0 and s_{wit} is negative.
- 3. If s_{wit} exists, return NO and otherwise YES.

For a transition system consisting of n states the preprocessing phase (step 1) can be done in time $O(n^2)$. The computation of step 2 can be performed in time $O(n^3)$ (basing on Bellman-Ford algorithm). Therefore the overall complexity of the algorithm is $O(n^3)$.

6 Concluding remarks

In this paper, we have investigated reversibility of transitions in bounded nets. In particular, we have shown that each transition in such nets can be reversed using a suitable set of new transitions, but not necessarily a single reverse transition. In future, we plan to investigate ways in which the generation of sets of reverses could be optimised.

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