

An S4F-related monotonic modal logic

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Abstract. This paper introduces a novel monotonic modal logic, allowing us to capture the nonmonotonic variant of the modal logic **S4F**: we add a second new modal operator into the original language of **S4F**, and show that the resulting formalism is strong enough to characterise the *logical consequence* of (nonmonotonic) **S4F**, as well as its *minimal model* semantics. The latter underlies major forms of nonmonotonic logic, among which are (reflexive) autoepistemic logic, default logic, and nonmonotonic logic programming. The paper ends with a discussion of a general strategy, naturally embedding several nonmonotonic logics of a similar floor structure on which a (maximal) *cluster* sits.

Keywords: nonmonotonic **S4F**, minimal model semantics, monotonic modal logic

1 Introduction

The use of monotonic modal logics for describing nonmonotonic inference has a long tradition in Artificial Intelligence. There exists a considerable amount of research in the literature [1,2,3,4,5,6,7,8], logically capturing important forms of nonmonotonic reasoning. Theoretically, we obtain a clear and simple monotonic framework for studying further language extensions and possible generalisations. From a practical point of view, we can check nonmonotonic deduction with a validity proving procedure in a corresponding monotonic setting.

The modal logic **S4F** (aka, **S4.3.2**) is obtained from **S4** by adding the axiom schema

$$F : (\varphi \wedge M\psi) \rightarrow L(M\varphi \vee \psi)$$

[9] in which L is the epistemic modal operator, and M is its dual, defined by $\neg L\neg$. A first and detailed investigation of this logic was given in [10]; yet in time, **S4F** has also found interesting theoretical applications in Knowledge Representation [11,12,13,14,15,16,17].

S4F is characterised by the class of Kripke models (W, \mathcal{T}, V) in which $W = W_1 \cup W_2$ for some disjoint sets W_1 and W_2 such that W_2 is nonempty. Moreover, $x\mathcal{T}y$ if and only if $y \in W_2$ or $x \in W_1$. V is the *valuation* function such that $V(x)$ is a set of propositional

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variables for every $x \in W$. A *cluster* is simply a trivial **S5** model (C, \mathcal{T}, V) such that $x\mathcal{T}y$ for every $x, y \in C$. In terms of Kripke semantics, **S5** is the modal logic, characterised by models in which the accessibility relation is an equivalence relation: it is reflexive, symmetric, and transitive. Now, we can alternatively identify an **S4F** model with the ordered triple (C_1, C_2, V) in which C_1 and C_2 are disjoint cluster structures, $C_2 \neq \emptyset$, and any world in C_2 can be accessed from every world in C_1 .

This paper follows a similar approach to [18] and [8]: the former captures the reflexive autoepistemic reasoning [19,20] of nonmonotonic **SW5** [21,22,23]. The latter successfully embeds equilibrium logic [24,25], which is a logical foundation for answer set programming (**ASP**) [26,27,28], into a monotonic bimodal logic called **MEM**. All these works are, in essence, parts of a project that aims to reexamine the logical and mathematical foundations of nonmonotonic logics. The overall project will then culminate in a single monotonic modal framework, enabling us to obtain a unified perspective of various forms of nonmonotonic reasoning.

As a reference to the analogy between all such works, we here keep the same symbols \mathcal{T} and \mathcal{S}^1 with [8,18] for the accessibility relations. Roughly speaking, [8,18] and this paper all propose Kripke models, composed of a union of 2-floor (disjoint) structures. In general, while the relation \mathcal{T} helps access from ‘bottom’ (*first floor*) to ‘top’ (*second floor*), the relation \mathcal{S} works in the opposite direction. However, the structures of bottom and top differ in all formalisms. In particular, the models here and in [18] are respectively the extensions of the Kripke models of **S4F** and **SW5** with the \mathcal{S} -relation; whereas **MEM** restricts top to a trivial cluster of a singleton, and forces all subsets of the top valuation to appear inside the bottom structure to check the minimality criterion of *equilibrium models* [24,25]. Similarly to [8,18], we also propose here a modal language $\mathcal{L}_{[\mathcal{T},\mathcal{S}]}$ with two (unary) modal operators, namely $[\mathcal{T}]$ and $[\mathcal{S}]$. The former is a direct translation of L in the language of **S4F** ($\mathcal{L}_{\mathbf{S4F}}$) into $\mathcal{L}_{[\mathcal{T},\mathcal{S}]}$ via a mapping ‘ $tr : \mathcal{L}_{\mathbf{S4F}} \rightarrow \mathcal{L}_{[\mathcal{T},\mathcal{S}]}$ ’. The relations \mathcal{T} and \mathcal{S} respectively interpret the modal operators $[\mathcal{T}]$ and $[\mathcal{S}]$. We call the resulting monotonic formalism **MLF**. We then add into **MLF** the *negatable axiom*, resulting in **MLF***: *modal logic of nonmonotonic S4F*. The negatable axiom ensures that the cluster C_1 (bottom) of **MLF** frames is nonempty, so it turns our frames into exactly 2-floor structures in **MLF***: both floors are maximal clusters w.r.t. the relation \mathcal{T} . Essentially, this axiom enables us to refute any nontautology of $\mathcal{L}_{[\mathcal{T},\mathcal{S}]}$ as it allows us to have all possible valuations in an **MLF*** model. Thus, we show that the formula $\langle \mathcal{T} \rangle [\mathcal{T}] (\varphi \wedge [\mathcal{S}] \neg \varphi)$ characterises maximal φ -clusters in **MLF***. This result paves the way to our final goal in which we capture nonmonotonic consequence (abbreviated ‘ $\approx_{\mathbf{S4F}}$ ’) of **S4F** in the monotonic modal logic **MLF***:

$$\varphi \approx_{\mathbf{S4F}} \psi \quad \text{if and only if} \quad [\mathcal{T}](tr(\varphi) \wedge [\mathcal{S}]\neg tr(\varphi)) \rightarrow [\mathcal{T}]tr(\psi) \text{ is valid in } \mathbf{MLF}^*.$$

The rest of the paper is organised as follows. Section 2 introduces the monotonic modal logic **MLF**: we first define its bimodal language, and then propose two classes of frames, namely **K** and **F**. They are respectively based on standard Kripke frames, and the cluster-based component frames, which are in the form of a floor structure. We axiomatise the validities of our logic, and finally prove that **MLF** is sound and complete

¹ The symbols \mathcal{T} and \mathcal{S} of [8] respectively refer to ‘*Top*’ and ‘*Subset*’. However, the relation \mathcal{S} has a different character and meaning in this paper, which is similar to those of [18].

w.r.t. both semantics. In Section 3, we extend **MLF** with the negatable axiom, and call the resulting logic **MLF***. We introduce two kinds of model structures, **K*** and **F***, and end with the soundness and completeness results. Section 3.1 recalls minimal model semantics of nonmonotonic **S4F**: we define the preference relation, and then give the definition of a minimal model for **S4F**. Section 3.2 first captures minimal models of **S4F**, and then embeds the consequence relation of **S4F** into **MLF***. Section 4 discusses a general approach, allowing us to capture major nonmonotonic logics. Section 5 makes a brief overview of this paper, and mentions our future goals.

2 A monotonic modal logic related to nonmonotonic S4F

We here propose a new formalism called **MLF**, which is closely associated with **S4F**.

2.1 Language ($\mathcal{L}_{[T],[S]}$)

Throughout the paper we suppose \mathbb{P} an infinite set of propositional variables, and \mathbb{P}_φ its restriction to those of a formula φ . We also consider *Prop* as the set of all propositional formulas of our language. The language $\mathcal{L}_{[T],[S]}$ is formally defined by the grammar:

$$\varphi ::= p \mid \neg\varphi \mid \varphi \rightarrow \varphi \mid [T]\varphi \mid [S]\varphi$$

where p ranges over \mathbb{P} . $\mathcal{L}_{[T],[S]}$ is therefore a bimodal language with the modalities [T] and [S]. As usual, $\top \stackrel{\text{def}}{=} \varphi \rightarrow \varphi$, $\perp \stackrel{\text{def}}{=} \neg(\varphi \rightarrow \varphi)$, $\varphi \vee \psi \stackrel{\text{def}}{=} \neg\varphi \rightarrow \psi$, $\varphi \wedge \psi \stackrel{\text{def}}{=} \neg(\varphi \rightarrow \neg\psi)$, and $\varphi \leftrightarrow \psi \stackrel{\text{def}}{=} (\varphi \rightarrow \psi) \wedge (\psi \rightarrow \varphi)$. Moreover, $\langle T \rangle\varphi$ and $\langle S \rangle\varphi$ respectively abbreviate $\neg[T]\neg\varphi$ and $\neg[S]\neg\varphi$.

2.2 Kripke semantics for MLF

We now describe the class **K** of Kripke frames for **MLF**. A **K-frame** is a triple $(W, \mathcal{T}, \mathcal{S})$:

- W is a non-empty set of possible worlds.
- $\mathcal{T}, \mathcal{S} \subseteq W \times W$ are binary relations such that for every $w, u, v \in W$,

$$\begin{array}{ll} (w, w) \in \mathcal{T} & \text{refl}(\mathcal{T}) \\ (w, u) \in \mathcal{T} \text{ and } (u, v) \in \mathcal{T} \Rightarrow (w, v) \in \mathcal{T} & \text{trans}(\mathcal{T}) \\ (w, u) \in \mathcal{T}, (u, w) \notin \mathcal{T} \text{ and } (w, v) \in \mathcal{T} \Rightarrow (v, u) \in \mathcal{T} & \text{f}(\mathcal{T}) \\ (w, u) \in \mathcal{S} \Rightarrow (u, u) \in \mathcal{S} & \text{refl}_2(\mathcal{S}) \\ (w, u) \in \mathcal{S} \text{ and } (u, v) \in \mathcal{S} \Rightarrow u = v & \text{wtriv}_2(\mathcal{S}) \\ (w, u) \in \mathcal{T} \Rightarrow (u, w) \in \mathcal{T} \text{ or } (u, w) \in \mathcal{S} & \text{msym}(\mathcal{T}, \mathcal{S}) \\ (w, u) \in \mathcal{S} \Rightarrow w = u \text{ or } (u, w) \in \mathcal{T} & \text{wmsym}(\mathcal{S}, \mathcal{T}). \end{array}$$

The first three properties above characterise the frames of the modal logic **S4F** [9]. Thus, a **K-frame** is an extension of an **S4F** frame by a second relation \mathcal{S} . Given a **K-frame** $\mathcal{F} = (W, \mathcal{T}, \mathcal{S})$, a **K-model** is a pair $\mathcal{M} = (\mathcal{F}, V)$ in which $V : W \rightarrow 2^{\mathbb{P}}$ is the map, assigning to each $w \in W$ a valuation $V(w)$. Then, given $w \in W$, a pointed **K-model** is a pair $\mathcal{M}_w = (\mathcal{M}, w)$, and similarly, a pointed **K-frame** is a pair $\mathcal{F}_w = (\mathcal{F}, w)$.

Truth conditions The truth conditions are standard: (for $p \in \mathbb{P}$)

$$\begin{aligned}
\mathcal{M}, w \models_{\text{MLF}} p & \quad \text{if } p \in V(w); \\
\mathcal{M}, w \models_{\text{MLF}} \neg\varphi & \quad \text{if } \mathcal{M}, w \not\models_{\text{MLF}} \varphi; \\
\mathcal{M}, w \models_{\text{MLF}} \varphi \rightarrow \psi & \quad \text{if } \mathcal{M}, w \not\models_{\text{MLF}} \varphi \text{ or } \mathcal{M}, w \models_{\text{MLF}} \psi; \\
\mathcal{M}, w \models_{\text{MLF}} [\text{T}]\varphi & \quad \text{if } \mathcal{M}, u \models_{\text{MLF}} \varphi \text{ for every } u \text{ such that } w\mathcal{T}u; \\
\mathcal{M}, w \models_{\text{MLF}} [\text{S}]\varphi & \quad \text{if } \mathcal{M}, u \models_{\text{MLF}} \varphi \text{ for every } u \text{ such that } w\mathcal{S}u.
\end{aligned}$$

We say that φ is **MLF satisfiable** if $\mathcal{M}, w \models_{\text{MLF}} \varphi$ for some **K**-model \mathcal{M} and w in \mathcal{M} . Moreover, φ is **MLF valid** (for short, $\models_{\text{MLF}} \varphi$) if $\mathcal{M}, w \models_{\text{MLF}} \varphi$ for every w of every **K**-model \mathcal{M} . Then, φ is valid in \mathcal{M} ($\mathcal{M} \models_{\text{MLF}} \varphi$) when $\mathcal{M}, w \models_{\text{MLF}} \varphi$ for every w in \mathcal{M} .

2.3 Cluster-based floor semantics for MLF

We here define the frames of a floor structure for **MLF**, and call their class **F**. The underlying idea is due to the property ‘f(\mathcal{T})’ of **K**-frames, and in fact, **F** is only a subclass of **K**. However, **F**-frames with some additional properties play an important role in the completeness proof. We now start with the definition of a \mathcal{T} -cluster² [22,29].

Definition 1. *Given a **K**-frame $(W, \mathcal{T}, \mathcal{S})$, let C be a subset of W . Then,*

- C is a \mathcal{T} -cluster if $w\mathcal{T}u$ for every $w, u \in C$;
- C is maximal if no proper superset of C in W is a \mathcal{T} -cluster.
- C is a \mathcal{T} -cone if for every $w \in W$, and every $u \in C$, $u\mathcal{T}w$ implies $w \in C$;
- C is final if $w\mathcal{T}u$ for every $w \in W$ and every $u \in C$.

It follows from Definition 1 that the restriction of \mathcal{T} to a \mathcal{T} -cluster C (abbreviated $\mathcal{T}|_C$) is a *universal* relation, viz. $\mathcal{T}|_C = C \times C$. So, (C, \mathcal{T}) happens to be a trivial **S5** frame.

Given a **K**-frame $\mathcal{F} = (W, \mathcal{T}, \mathcal{S})$, the relation \mathcal{T} partitions \mathcal{F} into disjoint subframes $\mathcal{F}' = (W', \mathcal{T}, \mathcal{S})$ in which $W' = C_1 \cup C_2$ for some maximal clusters $C_1, C_2 \subseteq W' \subseteq W$ such that $C_1 \cap C_2 = \emptyset$, and $C_2 \neq \emptyset$ is a final cone in W' . Thus, $\mathcal{T}|_{W'} = (W' \times C_2) \cup (C_1 \times C_1)$. We now define the operators $\mathcal{T}(\cdot), \mathcal{S}(\cdot) : 2^W \rightarrow 2^W$, respectively assigning to every $X \subseteq W$,

$$\begin{aligned}
\mathcal{T}(X) &= \{u \in W : w\mathcal{T}u \text{ for some } w \in X\}; \\
\mathcal{S}(X) &= \{u \in W : w\mathcal{S}u \text{ for some } w \in X\}.
\end{aligned}$$

When $X = \{w\}$, we simply write $\mathcal{T}(w)$ (resp. $\mathcal{S}(w)$), denoting the set of all worlds that w can access via \mathcal{T} (resp. \mathcal{S}). Note that $\mathcal{T}(\cdot)$ and $\mathcal{S}(\cdot)$ are homomorphisms under union:

$$\mathcal{T}(X \cup Y) = \mathcal{T}(X) \cup \mathcal{T}(Y) \quad \text{and} \quad \mathcal{S}(X \cup Y) = \mathcal{S}(X) \cup \mathcal{S}(Y).$$

We now formally define the above-mentioned partitions of a **K**-frame w.r.t. \mathcal{T} .

Definition 2. *Given a **K**-frame $\mathcal{F} = (W, \mathcal{T}, \mathcal{S})$, let $\mathbb{C} = (C_1, C_2)$ be a pair of disjoint subsets of W such that $C_2 \neq \emptyset$. Then, \mathbb{C} is called a component of \mathcal{F} if:*

1. C_1 and C_2 are maximal clusters;

² Unless specified otherwise, any definition of this paper is given w.r.t. the relation \mathcal{T} .

$$2. \mathcal{T} \cap (C_1 \times C_2) = C_1 \times C_2.$$

So, a component $\mathbb{C} = (C_1, C_2)$ has a ‘two-layered’ structure: C_1 is the *first floor* (‘F1-cluster’), and C_2 is the *second floor* (‘F2-cluster’). Clearly, C_2 is the final cone of the structure \mathbb{C} . Note that \mathbb{C} can also be transformed into a special \mathbf{K} -frame

$$\mathcal{F}^{\mathbb{C}} = (C_1 \cup C_2, ((C_1 \cup C_2) \times C_2) \cup (C_1 \times C_1), (C_2 \times C_1) \cup \Delta_{C_1}) \quad (1)$$

where Δ_{C_1} is the diagonal of $C_1 \times C_1$, i.e., $\Delta_{C_1} = \{(w, w) : w \in C_1\}$. Given any two different components $\mathbb{C} = (C_1, C_2)$ and $\mathbb{C}' = (C'_1, C'_2)$ of a \mathbf{K} -frame \mathcal{F} , $C_1 \cup C_2$ and $C'_1 \cup C'_2$ are disjoint, and \mathbb{C} and \mathbb{C}' are disconnected in the sense that there is no \mathcal{T} -access (nor an \mathcal{S} -access) from one to the other. As a result, a \mathbf{K} -frame \mathcal{F} is composed of an arbitrary union of components; however, when \mathcal{F} contains a component in which the F1-cluster is empty, and $\mathcal{S} \neq \emptyset$ (and so, \mathcal{S} is arbitrary), (1) is not sufficient to recover \mathcal{F} . This ambiguity in the transformation will be solved in the following section as the proposed logic \mathbf{MLF}^* does not accept components whose F1-cluster is empty.

Definition 3. An \mathbf{F} -frame is a pair $\mathbb{C} = (C_1, C_2)$, having a component structure.

We now define a function $\mu : \mathbf{F} \rightarrow \mathbf{K}$, assigning a \mathbf{K} -frame $\mu(\mathbb{C}) = \mathcal{F}^{\mathbb{C}}$ (see (1)) to each \mathbf{F} -frame \mathbb{C} . As two distinct components \mathbb{C} and \mathbb{C}' give rise to two distinct \mathbf{K} -frames $\mathcal{F}^{\mathbb{C}}$ and $\mathcal{F}^{\mathbb{C}'}$, μ is 1-1, but not onto³. Thus, \mathbf{F} is indeed a (proper) subclass of \mathbf{K} .

Proposition 1. Given a \mathbf{K} -frame $\mathcal{F} = (W, \mathcal{T}, \mathcal{S})$, let $\mathbb{C} = (C_1, C_2)$ be a component of \mathcal{F} , and $w \in C_1 \cup C_2$, then

1. if $w \in C_1$, then $\mathcal{T}(w) = C_1 \cup C_2$, and $\mathcal{S}(w) = \{w\}$;
2. if $w \in C_2$, then $\mathcal{T}(w) = C_2$, and $\mathcal{S}(w) = C_1$ when $C_1 \neq \emptyset$; otherwise $\mathcal{S}(w)$ is arbitrary.

The proof easily follows from the frame properties of \mathbf{K} .

Corollary 1. For a \mathbf{K} -frame $\mathcal{F} = (W, \mathcal{T}, \mathcal{S})$, and a component $\mathbb{C} = (C_1, C_2)$ of \mathcal{F} , we have:

1. $\mathcal{T}(C_1 \cup C_2) = C_1 \cup C_2$;
2. $\mathcal{S}(C_1 \cup C_2) \subseteq C_1 \cup C_2$.

Corollary 2. Given a pointed \mathbf{K} -frame \mathcal{F}_w , let $C = \mathcal{T}(w) \setminus C_1$ if w is in an F1-cluster C_1 ; else if w is in an F2-cluster C_2 , let $C = \mathcal{T}(w)$. Take $C' = \mathcal{S}(C) \setminus C$. Then, $\mathbb{C}^{\mathcal{F}_w} = (C', C) \in \mathbf{F}$.

Note that the component generated by $w \in \mathcal{F}$ is exactly the one in which w is placed. So, any point from the same component forms itself. Using Corollary 2, we now define another function ν , assigning to each pointed \mathbf{K} -frame \mathcal{F}_w an \mathbf{F} -frame $\mathbb{C}^{\mathcal{F}_w}$. Clearly, ν is not 1-1, but is onto. Finally, $\{\nu(\mathcal{F}_w) : w \in W\}$ identifies all the components in \mathcal{F} . The following proposition generalises this observation.

Proposition 2. Given an \mathbf{F} -frame $\mathbb{C} = (C_1, C_2)$ and $w \in C_1 \cup C_2$, we have $\nu(\mu(\mathbb{C}), w) = \mathbb{C}$.

³ Note that there is no \mathbf{F} -frame being mapped to (i) a \mathbf{K} -frame containing more than one component structure in it, and (ii) a \mathbf{K} -frame composed of only one component with a single (nonempty) cluster structure in which $\mathcal{S} \neq \emptyset$.

These transformations between frame structures of **MLF** enable us to define valuations also on the components $\mathbb{C} \in \mathbf{F}$, resulting in an alternative semantics for **MLF** via **F**-models. The new semantics can be viewed as a reformulation of the Kripke semantics: given a **K**-model $\mathcal{M} = (\mathcal{F}^{\mathbb{C}}, V)$ for some Kripke frame $\mathcal{F}^{\mathbb{C}} \in \mu(\mathbf{F})$ and a valuation V , one can transform $\mathcal{F}^{\mathbb{C}}$ to a component $v(\mathcal{F}_w^{\mathbb{C}}) = \mathbb{C} \in \mathbf{F}$ for some $w \in C_1 \cup C_2$ (see Proposition 2). This discussion allows us to define pairs (\mathbb{C}, V) in which $\mathbb{C} \in \mathbf{F}$, and V is the valuation restricted to \mathbb{C} . Such valuated components are called ‘**F**-models’, and they make it possible to transfer **K**-satisfaction to **F**-satisfaction.

Truth conditions (the modal cases) for an **F**-model $(\mathbb{C}, V) = (C_1, C_2, V)$ and $w \in C_1 \cup C_2$, $(\mathbb{C}, V), w \models_{\mathbf{MLF}} [T]\psi$ if and only if

- if $w \in C_1$ then $(\mathbb{C}, V), v \models_{\mathbf{MLF}} \psi$ for all $v \in C_1 \cup C_2$ (i.e., $(\mathbb{C}, V) \models_{\mathbf{MLF}} \psi$);
- if $w \in C_2$ then $(\mathbb{C}, V), v \models_{\mathbf{MLF}} \psi$ for all $v \in C_2$.

$(\mathbb{C}, V), w \models_{\mathbf{MLF}} [S]\psi$ if and only if

- if $w \in C_1$ then $(\mathbb{C}, V), w \models_{\mathbf{MLF}} \psi$;
- if $w \in C_2$ then $(\mathbb{C}, V), v \models_{\mathbf{MLF}} \psi$ for all $v \in C_1$ if $C_1 \neq \emptyset$; else ‘no strict conclusion’.

The next result reveals the relation between the Kripke and the floor semantics of **MLF**.

Proposition 3 (corollary of Proposition 2). *For an **F**-model (\mathbb{C}, V) , $w \in \mathbb{C}$, and $\varphi \in \mathcal{L}_{([T],[S])}$, $(\mathbb{C}, V), w \models_{\mathbf{MLF}} \varphi$ if and only if $(\mathcal{F}^{\mathbb{C}}, V), w \models_{\mathbf{MLF}} \varphi$.*

2.4 Axiomatisation of **MLF**

We here give an axiomatisation of **MLF**, and prove its completeness. Recall that $\mathbf{K}([T])$, $\mathbf{T}([T])$, $\mathbf{4}([T])$ and $\mathbf{F}([T])$ characterise the modal logic **S4F** [30]. The monotonic logic defined by Table 1 is **MLF**. The schemas $\mathbf{T}_2([S])$ and $\mathbf{WTriv}_2([S])$ can be combined

$\mathbf{K}([T])$	the modal logic K for [T]
$\mathbf{K}([S])$	the modal logic K for [S]
$\mathbf{T}([T])$	$[T]\varphi \rightarrow \varphi$
$\mathbf{4}([T])$	$[T]\varphi \rightarrow [T][T]\varphi$
$\mathbf{F}([T])$	$(\varphi \wedge \langle T \rangle [T]\psi) \rightarrow [T](\langle T \rangle \varphi \vee \psi)$
$\mathbf{T}_2([S])$	$[S]([S]\varphi \rightarrow \varphi)$
$\mathbf{WTriv}_2([S])$	$[S](\varphi \rightarrow [S]\varphi)$
$\mathbf{MB}([T], [S])$	$\varphi \rightarrow [T](\langle T \rangle \varphi \vee \langle S \rangle \varphi)$
$\mathbf{WMB}([S], [T])$	$\varphi \rightarrow [S](\varphi \vee \langle T \rangle \varphi)$

Table 1. Axiomatisation of **MLF**

into the axiom $\mathbf{Triv}_2([S])$, i.e., $[S]([S]\varphi \leftrightarrow \varphi)$, referring to the ‘‘triviality in the second **S**-step’’. Finally, $\mathbf{MB}([T], [S])$ and $\mathbf{WMB}([S], [T])$ are familiar from tense logics.

2.5 Soundness and completeness of MLF

The axiom schemas given in Table 1 precisely characterise the class \mathbf{K} of MLF frames. We only show that $F([T])$ describes the property $f(\mathcal{T})$ of \mathbf{K} -frames, but the rest is similar.

- Let $\mathcal{M}=(W, \mathcal{T}, \mathcal{S}, V)$ be a \mathbf{K} -model, satisfying $f(\mathcal{T})$. We want to show that $F([T])$ is valid in \mathcal{M} . Let $w \in W$ be such that $\mathcal{M}, w \models_{\text{MLF}} \varphi \wedge \langle T \rangle [T] \psi$ (\star). Then, it suffices to prove that $\mathcal{M}, w \models_{\text{MLF}} [T](\langle T \rangle \varphi \vee \psi)$. For an arbitrary $u \in W$, assume that $(w, u) \in \mathcal{T}$. Case (1): let $(u, w) \in \mathcal{T}$. The assumption (\star) implies that $\mathcal{M}, w \models_{\text{MLF}} \varphi$. Then, it also holds that $\mathcal{M}, u \models_{\text{MLF}} \langle T \rangle \varphi$; clearly, so does $\mathcal{M}, u \models_{\text{MLF}} \langle T \rangle \varphi \vee \psi$. Case (2): let $(u, w) \notin \mathcal{T}$. Then, by the assumption (\star), $\mathcal{M}, w \models_{\text{MLF}} \langle T \rangle [T] \psi$. Thus, there is $v \in W$ such that $(w, v) \in \mathcal{T}$ and $\mathcal{M}, v \models_{\text{MLF}} [T] \psi$. As \mathcal{M} satisfies $f(\mathcal{T})$, we get $(v, u) \in \mathcal{T}$. As $\mathcal{M}, v \models_{\text{MLF}} [T] \psi$, we have $\mathcal{M}, u \models_{\text{MLF}} \psi$; hence, $\mathcal{M}, u \models_{\text{MLF}} \langle T \rangle \varphi \vee \psi$.
- Let $\mathcal{F}=(W, \mathcal{T}, \mathcal{S})$ be a \mathbf{K} -frame in which $f(\mathcal{T})$ fails. So, there exists $w, u, v \in W$ with $(u, w) \notin \mathcal{T}$ while $(w, u) \in \mathcal{T}$ and $(w, v) \in \mathcal{T}$; yet $(v, u) \notin \mathcal{T}$. Thanks to the last 2 claims, we have $w \neq v$ (otherwise $(v, u) \notin \mathcal{T}$ would contradict $(w, u) \in \mathcal{T}$). Due to the first 2 claims, $w \neq u$ (otherwise, $(w, u)=(u, w)$, and $(u, w) \in \mathcal{T}$). We now take a valuation V satisfying: $\mathcal{M}, w \models_{\text{MLF}} \varphi$ (\blacktriangle), but $\mathcal{M}, x \not\models_{\text{MLF}} \varphi$ for any $x \neq w$; similarly, $\mathcal{M}, u \not\models_{\text{MLF}} \psi$ (\blacktriangledown), but $\mathcal{M}, y \models_{\text{MLF}} \psi$ for every $y \neq u$. Since $(v, u) \notin \mathcal{T}$, and thanks to the choice of V , $\mathcal{M}, v \models_{\text{MLF}} [T] \psi$. As $(w, v) \in \mathcal{T}$, and also by using (\blacktriangle), we have $\mathcal{M}, w \models_{\text{MLF}} \varphi \wedge \langle T \rangle [T] \psi$. On the other hand, $\mathcal{M}, u \not\models_{\text{MLF}} [T] \neg \varphi$ since $(u, w) \notin \mathcal{T}$ and w is the only point satisfying φ . Then, (\blacktriangledown) further implies that $\mathcal{M}, u \models_{\text{MLF}} [T] \neg \varphi \wedge \neg \psi$. Since $(w, u) \in \mathcal{T}$, we also get $\mathcal{M}, w \models_{\text{MLF}} \langle T \rangle ([T] \neg \varphi \wedge \neg \psi)$. So, we are done.

Corollary 3. *MLF is sound w.r.t. the class \mathbf{K} of frames.*

Here, we only need to show that the inference rules of MLF are validity-preserving.

Theorem 1. *MLF is complete w.r.t. the class of \mathbf{K} -frames.*

Proof. We use the method of canonical models (see [29]), so we first define the canonical model $\mathcal{M}^c = (W^c, \mathcal{T}^c, \mathcal{S}^c, V^c)$ in which

- W^c is the set of maximally consistent sets of MLF.
- \mathcal{T}^c and \mathcal{S}^c are the accessibility relations on W^c with:

$$\begin{aligned} \Gamma \mathcal{T}^c \Gamma' & \text{ if and only if } \{ \psi : [T] \psi \in \Gamma \} \subseteq \Gamma'; \\ \Gamma \mathcal{S}^c \Gamma' & \text{ if and only if } \{ \psi : [S] \psi \in \Gamma \} \subseteq \Gamma'. \end{aligned}$$

- V^c is the valuation s.t. $V^c(\Gamma) = \Gamma \cap \mathbb{P}$, for every $\Gamma \in W^c$.

By induction on φ , we prove a truth lemma saying: “ $\Gamma \models_{\text{MLF}} \varphi$ iff $\varphi \in \Gamma$ ” for every $\varphi \in \mathcal{L}_{[T],[S]}$. Then, it remains to show that \mathcal{M}^c satisfies all constraints of \mathbf{K} , and so is a legal \mathbf{K} -model of MLF. We here give the proof only for $\text{wtriv}_2(\mathcal{S})$ and $\text{wmsym}(\mathcal{S}, \mathcal{T})$.

► The schema $\text{WTriv}_2([S])$ guarantees that \mathcal{M}^c satisfies $\text{wtriv}_2(\mathcal{S})$: let $\Gamma_1 \mathcal{S}^c \Gamma_2$ (\star) and $\Gamma_2 \mathcal{S}^c \Gamma_3$ ($\star\star$). Assume for a contradiction that $\Gamma_2 \neq \Gamma_3$. Thus, there exists $\varphi \in \Gamma_2$ with $\neg \varphi \in \Gamma_3$, implying that $\langle S \rangle \neg \varphi \in \Gamma_2$ by the hypothesis ($\star\star$). Since Γ_2 is maximally consistent, $\varphi \wedge \langle S \rangle \neg \varphi \in \Gamma_2$. So, using the hypothesis (\star), we get $\langle S \rangle (\varphi \wedge \langle S \rangle \neg \varphi) \in \Gamma_1$.

However, since Γ_1 is maximally consistent, any instance of $\text{WTriv}_2([\text{S}])$ is in Γ_1 . Thus, $[\text{S}](\varphi \rightarrow [\text{S}]\varphi) \in \Gamma_1$, and it contradicts the consistency of Γ_1 .

► The schema $\text{WMB}([\text{S}], [\text{T}])$ ensures that $\text{wmsym}(\mathcal{S}, \mathcal{T})$ holds in \mathcal{M}^c : suppose that $\Gamma \mathcal{S}^c \Gamma' (\star)$ for $\Gamma, \Gamma' \in W^c$. W.l.o.g., let $\Gamma \neq \Gamma'$. Then, there exists $\psi \in \Gamma'$ with $\neg\psi \in \Gamma$. We need to show that $\Gamma' \mathcal{T}^c \Gamma$. So, let φ be such that $[\text{T}]\varphi \in \Gamma'$. As Γ' is maximally consistent, we have both $\varphi \vee \psi \in \Gamma'$ and $[\text{T}]\varphi \vee [\text{T}]\psi \in \Gamma'$. We know that $[\text{T}]\varphi \vee [\text{T}]\psi \rightarrow [\text{T}](\varphi \vee \psi)$ is a theorem of **MLF**, so it is in Γ' . Then, by Modus Ponens (MP), we get $[\text{T}](\varphi \vee \psi) \in \Gamma'$, further implying $(\varphi \vee \psi) \wedge [\text{T}](\varphi \vee \psi) \in \Gamma'$ since we already have $(\varphi \vee \psi) \in \Gamma'$. The assumption (\star) gives us that $\langle \text{S} \rangle((\varphi \vee \psi) \wedge [\text{T}](\varphi \vee \psi)) \in \Gamma$. Since Γ is maximally consistent, any instance of $\text{WMB}([\text{S}], [\text{T}])$ is in Γ ; in particular, so is $\langle \text{S} \rangle((\varphi \vee \psi) \wedge [\text{T}](\varphi \vee \psi)) \rightarrow (\varphi \vee \psi)$. Finally, again by MP, we have $\varphi \vee \psi \in \Gamma$. Since $\neg\psi \in \Gamma$, it follows that $\varphi \in \Gamma$.

Soundness and completeness of MLF w.r.t. F. Since any component $\mathbb{C} \in \mathbf{F}$ can be converted to a **K**-frame $\mu(\mathbb{C})$, soundness follows from Corollary 3 and Proposition 2. As to completeness, for a non-theorem $\varphi \in \mathcal{L}_{[\text{T}], [\text{S}]}$, $\neg\varphi$ is consistent. Let $\Gamma_{\neg\varphi}$ be a maximally consistent set in the canonical model \mathcal{M}^c such that $\neg\varphi \in \Gamma_{\neg\varphi}$. As the canonical frame $\mathcal{M}^c = (W^c, \mathcal{T}^c, \mathcal{S}^c)$ is a member of the class **K**, Proposition 1 and Proposition 2 allow us to define the component $\mathbb{C}^c = (C_1^c, C_2^c)$ with $\Gamma_{\neg\varphi} \in C_1^c \cup C_2^c$. Moreover, by Corollary 1, $C_1^c \cup C_2^c$ is closed under the operators $\mathcal{T}^c(\cdot)$ and $\mathcal{S}^c(\cdot)$. Therefore, modal satisfaction is preserved between \mathcal{M}^c and \mathbb{C}^c . As a result, $\mathbb{C}^c, \Gamma_{\neg\varphi} \not\models_{\text{MLF}} \varphi$ (i.e., $\mathbb{C}^c, \Gamma_{\neg\varphi} \models_{\text{MLF}} \neg\varphi$).

3 Where we capture nonmonotonic S4F: Modal logic **MLF***

We here propose an extension of **MLF** with a new axiom schema

$$\text{Neg}([\text{S}], [\text{T}]): \langle \text{T} \rangle [\text{T}]\varphi \rightarrow \langle \text{T} \rangle \langle \text{S} \rangle \neg\varphi$$

where $\varphi \in \text{Prop}$ is non-tautological. We call this schema ‘negatable axiom’ and the resulting formalism **MLF***. **MLF***-models are of 2 kinds, namely **K*** and **F***. They are obtained respectively from the classes **K** and **F** by adding a ‘model’ constraint:

$$\text{neg}(\mathcal{S}, \mathcal{T}): \text{for every } P \subseteq \mathbb{P}, \text{ there exists a world } w \text{ such that } P = V(w).$$

In other words, **MLF***-models can falsify any nontheorem of our logic, i.e., for every such φ , there exists a world w such that $w \models_{\text{MLF}^*} \neg\varphi$. Every **F***-model (C_1, C_2, V) now has an exactly ‘two-floor’ form: $C_1 \neq \emptyset$, and C_1 includes a world w , at which a propositional nontheorem φ , valid in C_2 , is refuted. A **K***-model is indeed an arbitrary combination of **F***-models. Below we show that $\text{Neg}([\text{S}], [\text{T}])$ precisely corresponds to $\text{neg}(\mathcal{S}, \mathcal{T})$.

Proposition 4. *Given a **K**-model $\mathcal{M} = (W, \mathcal{T}, \mathcal{S}, V)$ in **MLF**,*

$$\text{Neg}([\text{S}], [\text{T}]) \text{ is valid in } \mathcal{M} \text{ if and only if } \mathcal{M} \text{ is a } \mathbf{K}^* \text{-model.}$$

Proof. Let $\mathcal{M} = (W, \mathcal{T}, \mathcal{S}, V)$ be a **K**-model of **MLF**.

(\Rightarrow): Assume that \mathcal{M} is not a **K***-model. Then, there exists a nontautological propositional formula $\varphi \in \text{Prop}$ such that $\mathcal{M} \models_{\text{MLF}} \varphi$. Clearly, $[\text{T}]\varphi$, $[\text{S}]\varphi$ and $[\text{T}][\text{S}]\varphi$ are all

valid in \mathcal{M} , but then so is $\langle T \rangle [T] \varphi$ (thanks to the reflexivity of \mathcal{T}). This implies that $\langle T \rangle [T] \varphi \wedge [T] [S] \varphi$ is also valid in \mathcal{M} . Thus, $\text{Neg}([S], [T])$ is not valid in \mathcal{M} .

(\Leftarrow): Let \mathcal{M} be a \mathbf{K}^* -model (\bullet). Let $\varphi \in \text{Prop}$ be a nontheorem. Take $\beta = \langle T \rangle [T] \varphi \rightarrow \langle T \rangle \langle S \rangle \neg \varphi$. We need to show that $\mathcal{M} \models_{\text{MLF}^*} \beta$. Let $w \in W$ be such that $\mathcal{M}, w \models_{\text{MLF}^*} \langle T \rangle [T] \varphi$. We first consider the \mathbf{F} -model $\mathbb{C} = (C_1, C_2, V)$, generated by w as in Corollary 2. By construction, φ is valid in C_2 , and (\bullet) implies an existence of $u \in C_1$ such that u refutes φ . By the frame properties of \mathbf{F} , there exists $v \in C_2$ satisfying vSu and $\mathcal{M}, v \models_{\text{MLF}^*} \langle S \rangle \neg \varphi$. Regardless of the floor to which w belongs, wTv , and $v \in C_2$. Thus, $\mathcal{M}, w \models_{\text{MLF}^*} \langle T \rangle \langle S \rangle \neg \varphi$.

Proposition 5. *Given an \mathbf{F} -model $(\mathbb{C}, V) = (C_1, C_2, V)$ in MLF ,*

$\text{Neg}([S], [T])$ *is valid in (\mathbb{C}, V) if and only if (\mathbb{C}, V) is an \mathbf{F}^* -model.*

$\text{Neg}([S], [T])$ has an elegant representation. However, as it makes the reasoning clear in the demanding proofs of this section, we find it handier to use the equivalent version

$$\text{Neg}'([S], [T]): \langle T \rangle [T] \varphi \rightarrow \langle T \rangle \langle S \rangle (\neg \varphi \wedge Q)$$

of $\text{Neg}([S], [T])$ in which $\varphi \in \text{Prop}$ is a nontheorem, and Q is a conjunction of a finite set of literals (i.e., p or $\neg p$, for $p \in \mathbb{P}$) such that the set $\{\neg \varphi, Q\}$ is consistent.

Proposition 6. *For a \mathbf{K}^* -model $\mathcal{M} = (W, \mathcal{T}, S, V)$ and $w \in W$,*

$$\mathcal{M}, w \models_{\text{MLF}^*} \text{Neg}([S], [T]) \text{ if and only if } \mathcal{M}, w \models_{\text{MLF}^*} \text{Neg}'([S], [T]).$$

Proof. The right-to-left direction is straightforward: take $Q = \emptyset$ and the result follows. For the opposite direction, we first assume that $\mathcal{M}, w \models_{\text{MLF}^*} \text{Neg}([S], [T])$ (\blacktriangle). Let $\varphi \in \text{Prop}$ be a nontheorem of MLF^* viz. $\mathcal{M}, w \not\models_{\text{MLF}^*} \langle T \rangle [T] \varphi$ (\blacktriangledown). Let Q be a conjunction of finite literals such that $\neg \varphi \wedge Q$ is consistent. Then, $\varphi \vee \neg Q \in \text{Prop}$ is a nontheorem of MLF^* . Moreover, from the assumption (\blacktriangledown), we also get $\mathcal{M}, w \models_{\text{MLF}^*} \langle T \rangle [T] (\varphi \vee \neg Q)$. Lastly, by the hypothesis (\blacktriangle), we have $\mathcal{M}, w \models_{\text{MLF}^*} \langle T \rangle \langle S \rangle (\neg \varphi \wedge Q)$.

We finally transform a valuated cluster (C, V) into an \mathbf{F}^* -model. We first construct a set

$$C_1 = \{x_\varphi : \text{for every } \varphi \in \text{Prop} \text{ such that } \neg \varphi \not\vdash \perp, (C, V) \models_{\text{MLF}} \varphi \text{ and } x_\varphi \notin C\}$$

into which we put a point $x_\varphi \notin C$ for every nontheorem φ that is valid in C . So, $C \cap C_1 = \emptyset$. Then, we extend the universal relation \mathcal{T} on C to $\mathcal{T}' = ((C_1 \cup C) \times C) \cup (C_1 \times C_1)$ on $C \cup C_1$. The valuation V defined over C is also extended to $V' : C_1 \cup C \rightarrow \mathbb{P}$ satisfying: $V'|_C = V$, and $V'(x_\varphi)$ is designed to falsify φ . Hence, by definition, $(C_1, C, V') \in \mathbf{F}^*$.

Soundness and completeness of MLF^* We have seen that MLF is sound w.r.t. \mathbf{F} , so Proposition 5 implies that MLF^* is sound w.r.t. \mathbf{F}^* . Since any \mathbf{K}^* -model is a combination of \mathbf{F}^* -models, we can generalise this result to \mathbf{K}^* . We here show that MLF^* is complete w.r.t. \mathbf{F}^* : first we take a canonical model $\mathcal{M}^c = (W^c, \mathcal{T}^c, S^c, V^c)$ of MLF^* (see Theorem 1 for the details). Then, we define a valuated component $(\mathbb{C}^c, V^c) = (C_1^c, C_2^c, V^c)$ for $C_1^c, C_2^c \subseteq W^c$ as in Section 2.5. We want to show that (\mathbb{C}^c, V^c) is an \mathbf{F}^* -model. So, it is enough to prove that $\text{Neg}([S], [T])$ ensures the property $\text{neg}(S, \mathcal{T})$.

First recall that every **F**-frame \mathbb{C} corresponds to a **K**-frame $\mu(\mathbb{C}) = \mathcal{F}^{\mathbb{C}}$, and by Proposition 2, $\nu(\mu(\mathbb{C}), w) = \mathbb{C}$ for $w \in C_1 \cup C_2$. Thus, such $(\mu(\mathbb{C}^c), V^c)$ is a submodel of \mathcal{M}^c since it is a **K***-frame. For nontautological $\varphi \in Prop$, let us assume $\Gamma \models_{\text{MLF}^*} \varphi$ (i.e., $\varphi \in \Gamma$) for every $\Gamma \in C_2^c$ (so, φ is consistent). This implies that $(\mathbb{C}^c, V^c), \Gamma \models_{\text{MLF}^*} [\text{T}]\varphi$ (i.e., $[\text{T}]\varphi \in \Gamma$), for every $\Gamma \in C_2^c$. Using the fact that $\mu(\mathbb{C}^c)$ is part of the canonical model \mathcal{M}^c , we have $\mathcal{T}^c|_{C_1^c \cup C_2^c} \supset ((C_1^c \cup C_2^c) \times C_2^c)$. Thus, $(\mathbb{C}^c, V^c), \Gamma \models_{\text{MLF}^*} \langle \text{T} \rangle [\text{T}]\varphi$ for every $\Gamma \in C_1^c \cup C_2^c$. As any instance of $\text{Neg}([\text{S}], [\text{T}])$ is valid in (\mathbb{C}^c, V^c) , $\langle \text{T} \rangle \langle \text{S} \rangle \neg\varphi \in \Gamma$ for every $\Gamma \in C_1^c \cup C_2^c$. In other words, $(\mathbb{C}^c, V^c) \models_{\text{MLF}^*} \langle \text{T} \rangle \langle \text{S} \rangle \neg\varphi$. Thus, there exists $\Gamma' \in W^c$ such that $\Gamma' \mathcal{T}^c \Gamma''$ and $\Gamma'' \models_{\text{MLF}^*} \langle \text{S} \rangle \neg\varphi$ (i.e., $\langle \text{S} \rangle \neg\varphi \in \Gamma''$). As $\mathcal{T}(C \cup A) = C \cup A$ in **F**, we have $\Gamma' \in C_1^c \cup C_2^c$. Moreover, there also exists $\Gamma'' \in W^c$ such that $\Gamma' \mathcal{S}^c \Gamma''$ and $\Gamma'' \models_{\text{MLF}^*} \neg\varphi$. By Corollary 1, $\mathcal{S}(C_1^c \cup C_2^c) \subseteq C_1^c \cup C_2^c$, yet from our initial hypothesis, we obtain $\Gamma'' \in C_1^c$. To sum up, Γ'' is a maximally consistent set in \mathbb{C}^c such that $(\mathbb{C}^c, V^c), \Gamma'' \not\models_{\text{MLF}^*} \varphi$.

3.1 Minimal model semantics for nonmonotonic S4F

This section recalls the minimal model semantics for nonmonotonic **S4F** [22]. We first define a *preference* relation between **S4F** models, enabling us to check minimisation.

Definition 4. An **S4F** model $N = (N, R, U)$ is preferred over a valuated cluster (C, V) if

- $N = C \cup C_1$ for some (nonempty) set C_1 of possible worlds such that $C \cap C_1 = \emptyset$;
- $R = (N \times C) \cup (C_1 \times C_1)$;
- The valuations V and U agree on C (i.e., $V = U|_C$);
- There exists $\varphi \in Prop$ such that $C \models \varphi$ and $N \not\models \varphi$.

We abbreviate it by $N > (C, V)$. A valuated cluster (C, V) is then a *minimal model* of a theory (finite set of formulas) Γ in **S4F** if

- $(C, V), x \models \Gamma$ for every $x \in C$ (i.e., $(C, V) \models \Gamma$);
- $N \not\models \Gamma$ for every N such that $N > (C, V)$.

Finally, a formula φ is a *logical consequence* of a theory Γ in **S4F** (abbreviated $\Gamma \models_{\text{S4F}} \varphi$) if φ is valid in every minimal model of Γ . For example, $q \models_{\text{S4F}} \neg p \vee q$, yet $\neg p \vee q \not\models_{\text{S4F}} q$.

3.2 Embedding nonmonotonic S4F into MLF*

We here embed nonmonotonic **S4F** into **MLF***. With this aim, we first translate the language of **S4F** (\mathcal{L}_{S4F}) into $\mathcal{L}_{[\text{T}], [\text{S}]}$ via a mapping ‘*tr*’: we simply and only replace $L \in \mathcal{L}_{[\text{T}], [\text{S}]}$ by $[\text{T}]$. The following proposition proves that this translation is correct, and clarifies how to characterise minimal models of **S4F** in **MLF***.

Proposition 7. Given an **F***-model $(\mathbb{C}, V) = (C_1, C, V)$, and $\alpha \in \mathcal{L}_{\text{S4F}}$, we have:

1. $(\mathbb{C}, V), w \models_{\text{MLF}^*} \text{tr}(\alpha)$, for every $w \in C$ if and only if $(C, V|_C) \models \alpha$.
2. $(\mathbb{C}, V) \models_{\text{MLF}^*} \langle \text{T} \rangle [\text{T}](\text{tr}(\alpha) \wedge [\text{S}]\neg\text{tr}(\alpha))$ if and only if $(C, V|_C)$ is a minimal model of α .

Proof. The proof of the first item is by induction on α . As to the second item, for the proof of the ‘only if’ part, we first assume $(\mathbb{C}, V) \models_{\mathbf{MLF}^*} \langle \mathbf{T} \rangle [\mathbf{T}] (tr(\alpha) \wedge [\mathbf{S}] \neg tr(\alpha))$ (\blacklozenge).

(1) From (\blacklozenge), we obtain that $(\mathbb{C}, V), u \models_{\mathbf{MLF}^*} tr(\alpha)$ (\blacktriangle), and $(\mathbb{C}, V), u \models_{\mathbf{MLF}^*} [\mathbf{S}] \neg tr(\alpha)$ (\blacktriangledown) for every $u \in C$ (consider: for $w \in C_1$, (\blacklozenge) implies that there is $u \in C_1 \cup C$ such that $w \mathcal{T} u$ and $(\mathbb{C}, V), u \models_{\mathbf{MLF}^*} [\mathbf{T}] (tr(\alpha) \wedge [\mathbf{S}] \neg tr(\alpha))$. So, $u \in C$; otherwise it yields a contradiction). Then, using Proposition 7.1 and (\blacktriangle), we get $(C, V|_C) \models \alpha$. So, the first condition holds.

(2) By definition, it remains to show that $\mathcal{N} \not\models \alpha$ for every **S4F** model \mathcal{N} such that $\mathcal{N} \succ (C, V|_C)$. Let $\mathcal{N} = (N, R, U)$ be a preferred model over the valuated cluster $(C, V|_C)$ satisfying: $N = C \cup C'$ for some (cluster) C' such that $C \cap C' = \emptyset$, $R = (N \times C) \cup (C' \times C')$, and $U|_C = V|_C$. By Definition 4, we also know that there exists $\psi \in Prop$ such that $(C, V|_C) \models \psi$ (\bullet), but $\mathcal{N} \not\models \psi$. Therefore, there exists $r \in C'$ viz. $\mathcal{N}, r \not\models \psi$ (i.e., $\mathcal{N}, r \models \neg\psi$).

(3) As (\mathbb{C}, V) is an \mathbf{F}^* -model, $Neg([\mathbf{S}], [\mathbf{T}])$ is valid in it; due to Proposition 6, so is $Neg'([\mathbf{S}], [\mathbf{T}])$. Hence, $(\mathbb{C}, V) \models \langle \mathbf{T} \rangle [\mathbf{T}] \varphi \rightarrow \langle \mathbf{T} \rangle \langle \mathbf{S} \rangle (\neg\varphi \wedge Q)$ for a non-theorem $\varphi \in Prop$ of $\mathcal{L}_{\mathbf{MLF}^*}$, and a conjunction of a finite set of literals Q such that $\{\neg\varphi, Q\}$ is consistent.

(4) By (\bullet) in the item (2) and also using Lemma 7.1, we get $(\mathbb{C}, V), u \models_{\mathbf{MLF}^*} tr(\psi)$ for every $u \in C$. Since (\mathbb{C}, V) is an \mathbf{F}^* -model, we also have $(\mathbb{C}, V), u \models_{\mathbf{MLF}^*} [\mathbf{T}] tr(\psi)$; even $(\mathbb{C}, V), u \models_{\mathbf{MLF}^*} \langle \mathbf{T} \rangle [\mathbf{T}] tr(\psi)$ for every $u \in C$ (\clubsuit). Moreover, we know that $tr(\psi)$ is not a tautology; otherwise $\mathcal{N}, r \models \psi$. Let $Q' = \left(\bigwedge_{p \in (\mathbb{P}_\alpha \cap U(r))} p \right) \wedge \left(\bigwedge_{q \in (\mathbb{P}_\alpha \setminus U(r))} \neg q \right)$. It is clear that $\mathcal{N}, r \models Q'$, but we also know that $\mathcal{N}, r \models \neg\psi$, so we have $\mathcal{N}, r \models \neg\psi \wedge Q'$. We so conclude that $\{\neg\psi, Q'\}$ is consistent; then so is $\{\neg tr(\psi), Q'\}$. As (\mathbb{C}, V) is an \mathbf{F}^* -model, an instance of the negatable axiom, namely $\langle \mathbf{T} \rangle [\mathbf{T}] tr(\psi) \rightarrow \langle \mathbf{T} \rangle \langle \mathbf{S} \rangle (\neg tr(\psi) \wedge Q')$, is valid in (\mathbb{C}, V) . So, (\clubsuit) implies that $(\mathbb{C}, V), u \models_{\mathbf{MLF}^*} \langle \mathbf{T} \rangle \langle \mathbf{S} \rangle (\neg tr(\psi) \wedge Q')$ for every $u \in C$. This means that there exists a point $x_\psi \in C_1$ such that $(\mathbb{C}, V), x_\psi \models_{\mathbf{MLF}^*} \neg tr(\psi) \wedge Q'$, i.e., $(\mathbb{C}, V), x_\psi \models_{\mathbf{MLF}^*} \neg tr(\psi)$ and $(\mathbb{C}, V), x_\psi \models_{\mathbf{MLF}^*} Q'$. As a result, $V(x_\psi) \cap \mathbb{P}_{tr(\alpha)} = U(r) \cap \mathbb{P}_\alpha$.

(5) Note that r and x_ψ agree on \mathbb{P}_α . By (\blacktriangledown), we also have $(\mathbb{C}, V), x \models_{\mathbf{MLF}^*} \neg tr(\alpha)$ for every $x \in C_1$; in particular, $(\mathbb{C}, V), x_\psi \models_{\mathbf{MLF}^*} \neg tr(\alpha)$. To summarise the observation above:

1. The pointed model $((\{x_\psi\}, C, V|_{(C \cup \{x_\psi\})}), x_\psi)$ in \mathbf{MLF}^* , and the pointed model (\mathcal{N}, r) in **S4F** have the similar structure: both contain the same maximal valuated cluster $(C, V|_C)$ and one additional reflexive point that can have access to all points of C ;
2. $\mathbb{P}_\alpha = \mathbb{P}_{tr(\alpha)}$ and $V(x_\psi) \cap \mathbb{P}_{tr(\alpha)} = U(r) \cap \mathbb{P}_\alpha$;
3. Both α and $tr(\alpha)$ are the exact copies of each other, except that one contains L wherever the other contains $[\mathbf{T}]$ (note that $tr(\alpha)$ contains neither $[\mathbf{S}]$ nor $\langle \mathbf{S} \rangle$).

Then, it follows that $\mathcal{N}, r \not\models \alpha$, which further implies that $\mathcal{N} \not\models \alpha$. By definition, $(C, V|_C)$ is a minimal model for α . The other part of the proof is similar.

We are now ready to show how we capture the logical consequence of **S4F** in \mathbf{MLF}^* .

Theorem 2. For $\alpha, \beta \in \mathcal{L}_{\mathbf{S4F}}$, $\alpha \approx_{\mathbf{S4F}} \beta$ iff $\models_{\mathbf{MLF}^*} [\mathbf{T}] (tr(\alpha) \wedge [\mathbf{S}] \neg tr(\alpha)) \rightarrow [\mathbf{T}] tr(\beta)$.

Proof. We first take $\zeta = [\mathbf{T}] (tr(\alpha) \wedge [\mathbf{S}] \neg tr(\alpha)) \rightarrow [\mathbf{T}] tr(\beta)$.

(\Rightarrow): Assume that $\alpha \approx_{\mathbf{S4F}} \beta$ in **S4F** (\blacktriangle). Let $(\mathbb{C}, V) = (C_1, C_2, V)$ be an \mathbf{F}^* -model. Then $(C_2, V|_{C_2})$ is a valuated cluster over C_2 . We need to show that $(\mathbb{C}, V) \models_{\mathbf{MLF}^*} \zeta$. ‘‘For every $w \in C_1$, $(\mathbb{C}, V), w \models_{\mathbf{MLF}^*} \zeta$ ’’ trivially holds: by the frame constraints w.r.t. \mathcal{T} in \mathbf{MLF}^* , $(\mathbb{C}, V), w \not\models_{\mathbf{MLF}^*} [\mathbf{T}] (tr(\alpha) \wedge [\mathbf{S}] \neg tr(\alpha))$ for any $w \in C_1$ (otherwise, $(\mathbb{C}, V) \models_{\mathbf{MLF}^*} tr(\alpha)$, but also $(\mathbb{C}, V) \models_{\mathbf{MLF}^*} \neg tr(\alpha)$, yielding a contradiction). Let $x \in C_2$ be such that $(\mathbb{C}, V), x \models_{\mathbf{MLF}^*}$

$[T](tr(\alpha) \wedge [S]\neg tr(\alpha))$. We know that $\mathcal{T}|_{C_2}$ is a universal relation, so “for all $x \in C_2$, $(\mathbb{C}, V), x \models_{\mathbf{MLF}^*} \langle T \rangle [T](tr(\alpha) \wedge [S]\neg tr(\alpha))$ ” trivially follows. Then, by Proposition 7.2, we conclude that $(C_2, V|_{C_2})$ is a minimal model for α . Then, as $\alpha \vDash_{\mathbf{S4F}} \beta$ by the hypothesis (\blacktriangle) , β is valid in $(C_2, V|_{C_2})$, i.e., $(C_2, V|_{C_2}) \models \beta$. Thus, Proposition 7.1 gives us that $(\mathbb{C}, V), z \models_{\mathbf{MLF}^*} tr(\beta)$ for every $z \in C_2$. Since C_2 is a cluster which is a final cone, we also have $(\mathbb{C}, V), z \models_{\mathbf{MLF}^*} [T]tr(\beta)$ for every $z \in C$; in particular, $(\mathbb{C}, V), x \models_{\mathbf{MLF}^*} [T]tr(\beta)$.

(\Leftarrow) : Assume that ζ is valid in \mathbf{MLF}^* (\blacktriangledown) . We need to prove that $\alpha \vDash_{\mathbf{S4F}} \beta$. Let (C, V) be a minimal model of α . Then, we take an $\mathbf{S4F}$ model $\mathcal{N} = ((C \cup C'), R, U)$ preferred over (C, V) . viz. $\mathcal{N} > (C, V)$. Thus, $\mathcal{N} \not\models \alpha$ (\blacklozenge) . Now, let us construct $(\mathbb{C}, \bar{V}) = (C_1, C_2, \bar{V})$ as follows: take C_2 as the maximal α -cluster C (i.e., exactly the same cluster C as in (C, V)), and $C_1 = \{r : \mathcal{N}, r \not\models \alpha\}$. Simply, restrict R and U to $C_1 \cup C_2$, respectively resulting in \mathcal{T} and \bar{V} . Finally, arrange S in a way that would satisfy all the frame constraints of \mathbf{MLF} . Thus, (\mathbb{C}, \bar{V}) is clearly an \mathbf{F}^* -model. By the minimal model definition, $(C, V) \models \alpha$. Then, Proposition 7.1 and (\blacklozenge) imply that $(\mathbb{C}, \bar{V}), x \models_{\mathbf{MLF}^*} tr(\alpha)$ for every $x \in C_2$, and for every $y \in C_1$, $(\mathbb{C}, \bar{V}), y \models_{\mathbf{MLF}^*} \neg tr(\alpha)$. As (\mathbb{C}, \bar{V}) is an \mathbf{F}^* -model, we have $(\mathbb{C}, \bar{V}), x \models_{\mathbf{MLF}^*} [S]\neg tr(\alpha)$ for every $x \in C_2$. As a result, $(\mathbb{C}, \bar{V}), x \models_{\mathbf{MLF}^*} tr(\alpha) \wedge [S]\neg tr(\alpha)$ for every $x \in C_2$. Since C_2 is a cluster which is a final cone, we further have $(\mathbb{C}, \bar{V}), x \models_{\mathbf{MLF}^*} [T](tr(\alpha) \wedge [S]\neg tr(\alpha))$ for each $x \in C_2$. From (\blacktriangledown) , it also follows that $(\mathbb{C}, \bar{V}), x \models_{\mathbf{MLF}^*} [T]tr(\beta)$ for every $x \in C_2$. Clearly, $tr(\beta)$ is also valid in C_2 . Finally, Proposition 7.1 implies that $(C, V) \models \beta$ in $\mathbf{S4F}$.

Corollary 4. *For $\alpha \in \mathcal{L}_{\mathbf{S4F}}$, α has a minimal model if and only if $[T](tr(\alpha) \wedge [S]\neg tr(\alpha))$ is satisfiable in \mathbf{MLF}^* . (hint: take $\beta = \perp$ in Theorem 2.)*

4 Relation to other nonmonotonic formalisms

In this section, we briefly discuss a general strategy, unifying some major nonmonotonic reasonings among which are autoepistemic logic (**AEL**) [31], reflexive autoepistemic logic (**RAEL**) [23], equilibrium logic (and so **ASP**), and nonmonotonic **S4F**. The emphasis is on the 2-floor semantics; the second floor characterises the minimal model of a formula, and the first floor checks the minimality criterion. This approach can be generalised to other formalisms such as default logic [32] and **MBNF** [33] as there exists a good amount of research in the literature, studying such relations [34,35,36,15]. In particular, nonmonotonic **S4F** and default logic has a strong connection as it is explained and analysed in [14,15]. So, the \mathbf{MLF}^* encoding of nonmonotonic **S4F** leads the potential encoding of default logic.

AEL and **RAEL** [21,23] are the nonmonotonic variants [22] of respectively the modal logics **KD45** and **SW5** [9,29]. We have recently proposed two new monotonic modal logics called **MAE*** and **MRAE***, respectively capturing **AEL** and **RAEL**. They are obtained from \mathbf{MLF}^* by replacing only the axioms characterising **S4F** (i.e., S, 4, F) by ones, characterising respectively **KD45** and **SW5** (i.e., groups of axioms D, 4, 5 and T, 4, W5). The models of **MAE***, **MRAE***, and \mathbf{MLF}^* are all composed of a union of 2-floor structures: in each, the second floor is a maximal cluster which is a final cone of the 2-floor part of the model; where they differ is the structure of the first floor. While a first floor in \mathbf{MLF}^* is a maximal cluster, that of **MAE*** contains irreflexive and isolated worlds w.r.t. the \mathcal{T} -relation (in a sense that, any two different worlds of the

first floor are not related to each other by the accessibility relation \mathcal{T}). Moreover, the **MRAE*** models are nothing, but the reflexive closures of the **MAE*** models w.r.t. the relation \mathcal{T} . Interestingly, the same mechanism applied to **S4F** performs successfully for **KD45** and **SW5** as well when everything else remains the same: the implication $[T](tr(\alpha) \wedge [S]\neg tr(\alpha)) \rightarrow [T]tr(\beta)$, capturing nonmonotonic consequence of **S4F**, and the formula $\langle T \rangle [T](tr(\alpha) \wedge [S]\neg tr(\alpha))$ characterising minimal model semantics in **S4F** perfectly work for the nonmonotonic variants of **KD45** and **SW5** as well.

Our research has also a large overlap with [8], embedding equilibrium logic (and so, **ASP**) into a monotonic bimodal logic called **MEM**. The models of **MEM** are roughly described in the introduction. The main result of this paper is also given via a similar implication: the validity of $tr(\alpha) \wedge [S]\neg tr(\alpha) \rightarrow tr(\beta)$ in **MEM** captures the nonmonotonic consequence, $\alpha \vDash \beta$, of equilibrium logic. However, it is easy to check that the formula $[T](tr(\alpha) \wedge [S]\neg tr(\alpha)) \rightarrow [T]tr(\beta)$ of this paper also gives the same result. This analogy between all these works enables us to classify **MEM** under the same approach. Still, we need to provide a stronger result that would help reinforce the relations between **MEM** and **MLF***. For instance, [14] proves that the well-known Gödel’s translation into the modal logic **S4** is still valid for translating the logic of here-and-there (a 3-valued monotonic logic on which equilibrium logic is built) [37,25] into the modal logic **S4F**. A natural question that may arise is whether a similar translation can be used to encode **MEM** into **MLF***, which is the subject of a future work.

5 Conclusion and further research

In this paper, we design a novel monotonic modal logic, namely **MLF***, that captures nonmonotonic **S4F**. We demonstrate this embedding by translating the language of **S4F** into that of **MLF***. This way, we see that **MLF*** is able to characterise the existence of a minimal model as well as logical consequence in nonmonotonic **S4F**.

Our work provides an alternative to Levesque’s monotonic bimodal logic of only knowing [38,4,5,6], by which he captures four kinds of nonmonotonic logic, including autoepistemic logic: his language has two modal operators, namely **B** and **N**. **B** is similar to $[T]$. **N** is characterised by the complement of the relation, interpreting **B**. Levesque’s frame constraints on the accessibility relation differ from ours, and he identifies the nonmonotonic consequence ‘ $\alpha \vDash \beta$ ’ with the implication

$$(\mathbf{B} tr(\alpha) \wedge \mathbf{N} \neg tr(\alpha)) \rightarrow \mathbf{B} tr(\beta).$$

Levesque attacked the same problem with an emphasis on the only knowing notion. However, his reasoning does not attempt to unify, and does not provide a general mechanism either. In particular, he applied his approach to neither **SW5** nor **S4F**.

As a future work, we will implement this general methodology to capture minimal model reasoning, underlying many other nonmonotonic formalisms. This paper, together with other works on **KD45**, **SW5**, and **ASP** [8] stand a very strong initiative by their possible straightforward implementations to different kinds of nonmonotonic formalisms of similar floor-based semantics. Such research will then enable us to compare various forms of nonmonotonic formalisms in a single monotonic modal setting.

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