Utilizing Representation Learning for Robust Text Classification Under Datasetshift

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Abstract

Within One-vs-Rest (OVR) classification, a classifier differentiates a single class of interest (COI) from the rest, i.e. any other class. By extending the scope of the rest class to corruptions (dataset shift), aspects of outlier detection gain relevancy. In this work, we show that *adversarially trained autoencoders* (ATA) representative of autoencoder-based outlier detection methods, yield tremendous robustness improvements over traditional neural network methods such as multi-layer perceptrons (MLP) and common ensemble methods, while maintaining a competitive classification performance. In contrast, our results also reveal that deep learning methods solely optimized for classification, tend to fail completely when exposed to dataset shift.

Keywords

Dataset shift, Representation Learning, Outlier detection, One-vs-rest classification

1. Introduction

In recent years, deep neural networks (DNNs) have constantly achieved new SOTA results [1]. Despite these tremendous breakthroughs, they often fall behind expectations in reality[2].

Firstly, previous research exposed major blunders of DNNs providing wrong predictions with high confidence when exposed to dataset shift and adversarial examples [3, 4, 5, 6]. These robustness deficiencies can be visualized through the conceptual example in Fig. 1, in which the MLP has successfully learned to distinguish the XOR squares. However, when exposed to the uniform noise samples, the model wrongly classifies the noise with high confidence to belong to one of the two classes. Partially, this can be attributed to the softmax function as a fast-growing exponential function approximating a smooth indicator function, rendering predictions instable [3], and to the training process which is only separation oriented and focused on empirical risk minimization [7].

Secondly, models are often trained and evaluated in artificial environments, raising concerns on the transferability of the reported performances when applied in practice[2].

In this research paper, we investigate the issue of dataset shift robustness deficiencies for DNNs within the one vs rest (OVR) classification setting and empirically show that significant improvements can be achieved when incorporating reliable outlier detection techniques. By

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Figure 1: Class probabilities of MLP / MIMO and reconstruction errors of ATA / OCA visualized as contours on the noisy non-linear XOR squares dataset.

definition[8], outliers are samples that are generated from a completely different distribution than the inliers. Analogously, OVR classification aims to filter a single class of interest (COI) from the rest, i.e. all the remaining classes (RC). By incorporating out-of-distribution data within RC, i.e. classes unrelated to the training domain, methods from outlier detection gain relevancy. To evaluate the approaches w.r.t. classification and robustness performance, we depict a specific task for each concern: 1) For the classification task T_c , we evaluate the model on the classes it was trained on. 2) For the dataset shift task T_d , the model is evaluated on the inlier class of T_c and rest samples, i.e. outliers, derived from an unrelated dataset, similar to the evaluation approach in [3].

As previously shown by [9, 10, 11, 12, 13], autoencoder-based representation learning has been proven successful in detecting outliers. In this work, we utilize the two outlier detection methods *adversarially trained autoencoders* (ATA) [10] and *one class autoencoders* (OCA) to compare their classification and robustness performance to MLPs and the recently published ensemble method MIMO[14]. In contrast to the semi-supervised OCA, ATA not only minimizes the reconstruction error of COI samples but also actively maximizes the reconstruction error of RC samples, thereby making the reconstruction error a richer outlierness feature, especially when COI samples are correlated with RC samples.

Our contributions are summarized as follows: We show that traditional DNNs such as MLP and ensemble methods are highly unreliable when exposed to dataset shift. As a viable solution, we propose autoencoder-based outlier detection methods to OVR classification resulting in accurate classifiers that are highly robust to dataset shift. Furthermore, our results indicate that robustness can slightly harm classification performance, which is in line with previous research results [15, 16].

2. Adversarially Trained Autoencoders

Adversarially trained autoencoders (ATA) have been proven to be highly effective for outlier detection by incorporating a priori outlier information into the training process[10, 11]. While semi-supervised methods such as OCA, minimize the reconstruction loss $L_{\text{MSE}}(\mathbf{x}, \hat{\mathbf{x}}) = \frac{1}{n} \sum_{i}^{n} (x_i - \hat{x}_i)^2$ for samples $\mathbf{x} \in$ inliers only, ATA additionally maximizes the L_{MSE} for outliers. Given sample \mathbf{x} , its reconstruction $\hat{\mathbf{x}}$ and target t, the so called adversarial loss function computes to

$$L_{adv}(\mathbf{x}, \hat{\mathbf{x}}, t) = \begin{cases} 0, & L_{\text{MSE}} \in [\mathbf{l}, \mathbf{u}] \quad \wedge \quad t \in \text{outliers} \\ L_{\text{MSE}}(\mathbf{x}, \hat{\mathbf{x}}), & L_{\text{MSE}}(\mathbf{x}, \hat{\mathbf{x}}) \ge u \quad \lor \quad t \in \text{inliers} \\ -\alpha L_{\text{MSE}}(\mathbf{x}, \hat{\mathbf{x}}), & \text{otherwise}, \end{cases}$$
(1)

where outlier weighting factor α determines the outlier maximization intensity. This loss function captures the reconstruction error of outliers within the bounds l, u, by maximizing / minimizing the reconstruction loss accordingly, as unlimited maximization could lead to exploding gradients. Inlier samples are generally minimized. The network architecture is given by

$$f(\mathbf{x}) = e_{\text{MSE}}(\mathbf{x}, d(e(\mathbf{x}))), \tag{2}$$

where $e_{\text{MSE}}(\mathbf{x}, \hat{\mathbf{x}}) = \frac{1}{n} \sum_{i}^{n} (x_i - \hat{x}_i)^2$ is the reconstruction error, which takes a sample \mathbf{x} and its reconstruction $\hat{\mathbf{x}}$ as input. The reconstruction is provided by the autoencoder defined by the nesting of the decoder d and encoder e.

Since ATA does not build upon unstable output functions like softmax[3] and learns a concrete representation of the COI, it is by design more robust to corruptions compared to other deep learning models like MLPs or ensemble methods like MIMO[14]. This makes ATA not only a compelling method for outlier detection but also a robust method for OVR.

3. Experiments and Results

To compare ATA to the three baselines MLP, MIMO and OCA on an algorithmic rather than model level, we perform nested cross validation (CV) [17]. For each algorithm, we select the best models by the *area under the precision recall curve* (AUPR) and report the score aside with *area under the receiver operating characteristics* (AUROC) and F1 score. AUPR and F1 score are calculated w.r.t. COI. Since AUROC and AUPR are threshold-independent, they yield a more comprehensive evaluation compared to e.g., F1 score. Unlike AUROC, AUPR takes the base rate of the positive class into account and thus is more applicable to settings with high class imbalance[3]. AUROC can be interpreted as the probability of ranking a random positive sample higher than a random negative sample[18].

For a fair comparison, ATA and the baselines are defined to have a comparable parameter complexity. MIMO, MLP, as well as decoder and encoder (but in reverse) each possess three hidden layers of size 50, 25 and 12 with sigmoid activations. Due to its five parallel input layers, MIMO has the highest number of trainable parameters. All approaches have a binary output, which alleviates aforementioned softmax stability. As part of the nested CV, all algorithms were hyperparameter-tuned w.r.t. *learning rate* and *weight decay*. Additionally, ATA was optimized for *outlier weighting factor* and *bin range*.

	A	TIS	R	euters	New	Newsgroups				
	Rest	COI	Rest	COI	Rest	COI				
Train/ S_c	a_c	flight	r_c	acq, earn	n_c	sci.space				
S_{d1}	t_d	flight	t_d	acq, earn	t_d	sci.space				
S_{d2}	r_d	flight	a_d	acq, earn	a_d	sci.space				
S_{d3}	n_d	flight	n_d	acq, earn	r_d	sci.space				

Table 1

Class assignment within splits S_c , S_{d1} , S_{d2} and S_{d3} for each dataset: Splits S_c and S_d are representative of tasks T_c and T_d , respectively. Mapping of rest classes specified in Tabl. 2

Dataset	Abbr.	Rest labels						
Reuters	r_c r_d	crude, interest, money-fx, money-supply, ship, retail, wpi, cpi, jobs, cotton, ipi, reserves tin, carcass, housing, nat-gas, pet-chem, oilseed, rubber, orange, lumber, livestock, heat trade, grain, ship, gold, interest, money-fx, money-supply, jobs, sugar, tin, ipi, cpi, coco fee, cotton, coppper, alum, rubber, yen, nat-gas,reserves						
ATIS	$egin{array}{c} a_c \ a_d \end{array}$	airfare, ground_service, airline abbreviation, restriction, airport, quantity, meal, city, flight_no, ground_fare, flight_time, flight, distance, aircraft, capacity						
News groups	n _c n _d	sci.crypt, sci.med, talk.politics.guns, misc.forsale, rec.sport.baseball, talk.politics.misc, comp.os.ms-windows.misc, soc.religion.christian rec.sport.hockey, sci.crypt, sci.med, comp.sys.ibm.pc.hardware, talk.politics.mideast, comp.sys.mac.hardware, rec.autos, sci.electronics, talk.religion.misc, alt.atheism, rec.motorcycles, comp.windows.x, comp.graphics, sci.space, talk.politics.guns, misc.forsale, rec.sport.baseball, talk.politics.misc, comp.os.ms-windows.misc, soc.religion.christian						
TREC ⁴	t_d	HUM, NUM, LOC, ABBR						

Table 2

Indicated by the matching indices, rest labels of each dataset for each of the splits S_c , S_{d1} , S_{d2} and S_{d3} , as specified in Tabl. 1.

3.1. Datasets

To evaluate dataset shift robustness, we consider the three textual datasets Reuters¹, ATIS² and Newsgroups³. As shown in Tabl. 1 and Tabl. 2, the COI always deals with a very narrow topic and rest samples originate from a diverse set of classes, as characteristic for OVR. Split S_c resembles the classification task T_c since it contains all training classes. Splits S_{d1} , S_{d2} and S_{d3} , representative of dataset shift task T_d , contain rest samples from a novel dataset, similar to [3].

3.2. Results

As summarized in Tabl.3, MIMO and MLP yield strong classification results on T_c , which however is tainted by significant performance degradation when exposed to dataset shift within T_d . Conversely, OCA provides strong robustness during dataset shift exposure, whereas fails completely on task T_c .

¹http://www.daviddlewis.com/resources/testcollections/reuters21578/

 $^{^{2}}http://www.ai.sri.com/natural-language/projects/arpa-sls/atis.html$

³http://qwone.com/ jason/20Newsgroups/

	ATIS					REUTERS					Newsgroups						
	AUROC		AUPR		F1 Score		AUROC AUPR		J PR	F1 Score		AUROC		AUPR		F1 Score	
OCA	99.3 98.9	$\pm 0.6 \\ \pm 2.2 \\ \pm 0.1 \\ \pm 0.2$	98.9 91.3 99.8 99.8 81.9	$\pm 0.2 \\ \pm 1.2 \\ \pm 0.0 \\ \pm 0.0$	92.0 64.3 98.0 97.8 31.0	$\pm 0.7 \\ \pm 1.7 \\ \pm 0.4 \\ \pm 0.1$	$\begin{array}{r} 99.4 \ \pm \ 0.1 \\ \textbf{82.3} \ \pm \ 4.7 \\ \textbf{99.7} \ \pm \ 0.1 \\ 99.6 \ \pm \ 0.1 \\ 50.0 \end{array}$	99.8 94.3 99.9 99.9 77.3	$\pm 0.0 \\ \pm 2.0 \\ \pm 0.1 \\ \pm 0.0$	97.8 76.1 99.0 98.7 30.4	$\pm 0.6 \\ \pm 3.5 \\ \pm 0.3 \\ \pm 0.1$	94.8 67.7 97.5 97.3 50.0	\pm 1.6 \pm 2.1 \pm 0.4 \pm 0.5	86.7 29.2 90.9 89.6 11.4	\pm 2.1 \pm 2.8 \pm 0.6 \pm 1.2	74.7 30.0 79.2 82.3 9.3	$\pm 2.9 \\ \pm 4.3 \\ \pm 1.7$
ATA OCA S_{d1} MLP MIMO BASE	73.1 81.4	$\pm 0.1 \\ \pm 0.2 \\ \pm 8.2 \\ \pm 2.0$	96.8 96.5 37.4 41.0 20.9	$\pm 0.5 \\ \pm 0.3 \\ \pm 7.7 \\ \pm 3.4$	90.5 66.1 46.3 44.8 14.7	$\pm 0.4 \\ \pm 1.6 \\ \pm 3.3 \\ \pm 1.3$	$\begin{array}{r} 97.6 \ \pm \ 1.3 \\ \textbf{98.6} \ \pm \ 0.2 \\ 90.1 \ \pm \ 1.8 \\ 93.1 \ \pm \ 2.2 \\ 50.0 \end{array}$		$\pm 1.6 \\ \pm 0.4 \\ \pm 6.3 \\ \pm 5.0$	74.2 77.5 67.0 59.0 18.4	$\pm 12.4 \\ \pm 3.1 \\ \pm 1.8 \\ \pm 2.9$	97.2 99.3 91.3 84.6 50.0	$egin{array}{c} \pm \ 0.6 \\ \pm \ 0.5 \\ \pm \ 2.9 \\ \pm \ 1.7 \end{array}$		$\pm 1.8 \\ \pm 0.6 \\ \pm 5.7 \\ \pm 4.5$	70.3 41.9 40.9 28.1 5.4	$\pm 3.8 \\ \pm 8.9 \\ \pm 2.3$
OCA	95.9	$\pm 0.2 \\ \pm 0.5 \\ \pm 10.0 \\ \pm 1.1$	94.3	$\pm 0.3 \\ \pm 0.5 \\ \pm 16.3 \\ \pm 2.6$	92.5 66.1 64.5 75.1 20.5	$\pm 0.6 \\ \pm 1.6 \\ \pm 5.5 \\ \pm 3.1$	$\begin{array}{r} \textbf{98.5} \ \pm \ 0.9 \\ \textbf{98.5} \ \pm \ 0.3 \\ \textbf{84.2} \ \pm \ 5.6 \\ \textbf{83.8} \ \pm \ 7.8 \\ \textbf{50.0} \end{array}$	49.2	$\pm 1.5 \\ \pm 0.5 \\ \pm 16.0 \\ \pm 16.8$	75.6 77.5 47.5 39.8 15.1	$\pm 13.2 \\ \pm 3.1 \\ \pm 4.4 \\ \pm 2.0$	90.2 99.4 81.4 60.0 50.0	$\pm 2.0 \\ \pm 0.5 \\ \pm 11.1 \\ \pm 3.5$	38.8 99.1 20.3 9.7 4.2	$\pm 4.0 \\ \pm 0.6 \\ \pm 18.8 \\ \pm 5.9$	26.9 41.9 18.8 8.1 3.9	$\pm 3.8 \pm 5.7$
	92.7	$\pm 2.0 \\ \pm 0.6 \\ \pm 8.1 \\ \pm 2.1$	82.4 83.1 12.7 57.8 4.1	$\pm 4.8 \\ \pm 1.0 \\ \pm 12.9 \\ \pm 8.2$	50.6 66.1 9.2 11.9 3.8	$\pm 17.5 \\ \pm 1.6 \\ \pm 1.3 \\ \pm 1.8$	$\begin{array}{l} \textbf{94.3} \ \pm \ 2.6 \\ \textbf{87.2} \ \pm \ 8.5 \\ \textbf{97.1} \ \pm \ 1.1 \\ \textbf{95.0} \ \pm \ 4.1 \\ \textbf{50.0} \end{array}$	67.6	\pm 1.8 \pm 18.9 \pm 13.3 \pm 10.2		$\pm 10.5 \\ \pm 21.4 \\ \pm 4.4 \\ \pm 2.1$	96.2 98.8 95.8 88.8 50.0	$\pm 1.0 \\ \pm 0.7 \\ \pm 2.1 \\ \pm 2.1$	78.7 98.1 74.0 57.9 11.5	$\begin{array}{c} \pm \ 2.8 \\ \pm \ 0.8 \\ \pm \ 8.8 \\ \pm \ 11.8 \end{array}$	71.8 41.9 69.8 56.5 9.3	$\pm 3.8 \pm 9.6 \pm 4.6$

Table 3

Performance of ATA and baselines on splits S_c , S_{d1} , S_{d2} and S_{d3} : Across the two subtasks of OVR, ATA yields robust results, while MLP/ MIMO and OCA show a significant performance degradation on the dataset shift and classification task, respectively. Metrics and confidence reported in %. Failures highlighted in red for AUROC < 90%. AUPR and F1 score failures due to base rate dependency not considered. BASE resembles a random classifier predicting COI with probability $p \sim U[0, 1]$ for reference.

In contrast, ATA represents an effective trade-off between classification performance and robustness to dataset shift. The results are always at least close to the best performing model on each task and never show complete model failures. On the contrary, MLP and MIMO each fail in terms of AUROC on T_d in 5/9 cases. Analogously, OCA fails in all cases on task T_c .

The results are well-aligned with the visualization in Fig. 1, in which MLP, MIMO and ATA are capable of separating the inlier class from the rest class, however, in a fundamentally different fashion. ATA learns a hull around the COI samples and therefore is able to reject the rest class including any corruptions. This is also reflected in the experiments, in which ATA not only provides a strong performance on the classification task but also higher robustness on the dataset shift task. The contours of OCA in Fig. 1, reveal a major overlap of COI and rest class, as rest samples get minimized implicitly when minimizing COI. This inherent problem is also present in the experiments, where OCA is robust to corruptions, but consistently fails on T_c .

4. Conclusion

We investigated model robustness on one-vs-rest classification by extending the scope of the rest class to strong corruptions (dataset shift). We find that conventional DNNs such as MLP and deep ensembles (MIMO), provide highly unstable predictions when exposed to dataset shift.

With ATA, as an outlier detection method based on autoencoders, we showed that tremendous robustness improvements can be achieved, while slightly compromising classification performance. Especially in safety-related and volatile environments with model robustness as a principal concern, ATA poses a worthwhile consideration.

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