Invited Talk

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Semantics of movement patterns

In this talk I will discuss progress in research relating to the semantics associated with patterns of moving objects. The talk will highlight how time in particular serves as an important foundation for extracting many different kinds of moving object semantics. I will discuss different temporal data models and how the choice of models exposes different moving object semantics.

Patterns of Moving Objects: Why so interesting?

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Moving objects

- Major research effort by numerous researchers that relates to analyzing and simulating different behaviors and activities through space-time
- Many of these studies involve modeling the movement of objects (people, vehicles, animals, natural phenomena) through a territory affording a focus on e.g.,
 - * The trajectory or path of movement
 - Movement in constrained vs. unconstrained environments
 - * Movement of individuals vs. groups
 - * Uncertainty of movement
 - * Spatiotemporal patterns of movement

Today's talk

- Discuss the topic of patterns of moving objects with a particular focus on semantics
 - Discuss semantics from the perspective of some of the underlying temporal data models that are possible for moving object applications
 - * Spatiotemporal patterns of movement
- Highlight the semantics that arise from
 - * Modeling linear sequences
 - * Branching
 - * Modeling cycles

Today's talk

* In addition...

 Provide a critical overview of progress and shortcomings relating to semantics that is relevant to movement pattern analysis

Modeling movement

Many efforts to model the movement of objects



Gulf of Mexico Oil spill July 2010



Ships through harbor waters



Track that car

Formalizations designed to reveal different semantics



Here elements of a trajectory are formalized including **Begin**, **End**, **Stop**, **Move**

Semantic trajectory ontology from Yan, Macedo, Parent, Spaccapietra Transactions in GIS, 12: 75-91.

Activities and trips



Trip

Which activities, of the person p during the day d, takes place at a given location of the place x ?

Activities_At_Point(TP.traj, PL.x) | TP \in TimePath \land PL \in place \land TP.idPers = $p \land$ TP.day = d

Sheni, Frihida, Ben Ghezala, and Claramunt (2009) ER 2009 Workshops, pp. 347-356.

A common interest...stops or stay points



http://research.microsoft.com/apps/pubs/? id=79440 Y. Zheng and X. Xie (2009)

Alternatively...

The path of the moving object is captured through an expression such as

$$\begin{cases} e_{t1}^{zone}, e_{t2}^{zone}, \dots, e_{tn}^{zone} \end{cases} \text{ where,} \\ e_{t1}^{zone} < e_{t2}^{zone} < \dots < e_{tn}^{zone} \end{cases} e_{tn}^{zone}$$







Event-based model of movement

This transit through a harbor can be modeled as a sequence of events

FRY CZE inbd_SE_TSS	< _{FRV} cze	precautionary t2	$< _{FRY}$	CZe approach	<
FRY	$cze_{t4}^{bay} <$	$_{FRY}^{FRY} CZe_{t5}^{an}$	ichorage		





This allows us to model important characteristics of many different kinds of movements

A vessel enters the harbor waters and then leaves again without ever reaching its intended destination



$$\begin{array}{c|c} \begin{array}{c} \begin{array}{c} oldZone: offshore \\ FRY1 \end{array} dep \end{array} \begin{array}{c} \begin{array}{c} inbd_W_TSS \\ t1 \end{array} < \begin{array}{c} FRY1 \end{array} cze \end{array} \begin{array}{c} precautionary \\ t2 \end{array} < \\ \end{array} \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \begin{array}{c} expectedNext: approach \\ FRY1 \end{array} \end{array} \begin{array}{c} \begin{array}{c} \begin{array}{c} outbd_SE_TSS \\ t3 \end{array} \end{array} \\ \end{array} \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} expectedDest: \ ferryLanding \\ t4 \end{array} \end{array} \\ \end{array} \\ \begin{array}{c} \begin{array}{c} ude \end{array} \begin{array}{c} offshore \\ t4 \end{array} \\ \end{array} \\ \end{array} \\ \end{array}$$

And develop typologies of movement



Relative Motion Patterns



Laube, P., and Imfeld, S. (2002) Proceedings of GIScience 2002, 132-144.

Speed, acceleration, and movement direction



Dodge, S., Weibel, R., and Lautenschütz, A-K. (2008) Towards a taxonomy of movement patterns, Information Visualization, 7, 240-252

Much of this work assumes one thing...

* An underlying **linear model** of time



- focus on *before* and *after* relations
- Useful for timeline applications
- Temporal and spatial patterns of events commonly represented in simulations



Oculus's **GeoTime** application www.oculusinfo.com

Another model

- * Let's consider another temporal model that will
- support additional semantics important for moving object applications and
- * give rise to distinct patterns of movement

Branching events model

- * Work underway with Shane Hubbard, Ulowa
- * This model captures **spatiotemporal alternatives**
 - * E.g., what behaviors might occur in the **future** or what might have happened in the **past**
 - Has two key elements
 - * Diverging
 - ***** Converging



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Spatiotemporal alternatives



- Now possible future events including movements can be modeled
- Useful for "what if?"
 modeling
- Richer set of behaviors

Spatiotemporal alternatives



- Can explore how many alternatives exist for a given time
- How many alternatives are associated with a **given location** over time

Sometimes something else is needed...

- * The linear and branching models emphasize sequences
- * Want to capture the **repetitions** that are commonly present in behaviors and movements
- Need to expand modeling to allow for cycles



Spatiotemporal cycles are commonplace

- A ferry or ship's movement in and out of the harbor may be cyclic
- Repeating events, locations, or times
 - * Same event, same time, same location
 - * Same event, different time, same location
- * Granularity matters...
 - * Individual or **paths**,
 - Event times, dates, combinations of both
 - * Cycle times, dates





t

 In a set of events, certain events may initiate a cycle, e.g.,

 ${}^{oldZone:offshore}_{WFG} dep^{inbd}_{t_1} {}^{SE} {}^{TSS}$

Other events will terminate a cycle, e.g.,

 $\begin{array}{c} \exp{\textit{ectedDest:anchorage}}\\ WFG \\ WFG \\ t_{5} \end{array}$

- And an **interval** often exists between repetitions (granularity again...)
 - * Continous cycles (daily ferry service),
 - intermittent cycles (seasonal ferry service)



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Interesting cases





Interrupted cycles

Partially completed Initiating, no terminating

Branching events and cycles

* The parameters of t and I for time and location respectively are obviously very key here...and granularity matters

- t= time (st; et; (st,et); date; timestamp)
- I = location (x,y coordinates; region; path)
- Also the granularity of the entity of interest
 - * Individual events? Several branches? Entire cycle?

Duration of events

- This temporal aspect is key for both branching and cycles
- Different durations will result in branches of different lengths of time



And in cycles of different lengths

16 Cyclic Interval Relations ((Stewart) Hornsby et al. 1999)



- For a single moving object, can compare 2 or more branches and represent possible relations between branches
 - * Capture similarities or differences
- * Can compare 2 or more **paths** that are **cyclic** and look for relations between routes
- Compare paths of different objects
 Maximize or minimize certain relations (e.g., to avoid gaps in route coverage)





Summary

- A linear temporal model is most commonly used as the basis for modeling moving objects
- Additional data models are possible and reveal additional semantics
 - * **Branching model captures semantics of spatiotemporal alternatives**
 - * and cyclic model captures semantics for repeating movements
- Identify primitives for modeling
 - time, location, identity, diverging, converging, initiating, terminating, stops, moves, activities
- Need to account for granularity of time and location, event durations, interruptions (branching and cyclic)
- Ongoing: spatiotemporal patterns in landscapes of risk and opportunity



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