

An Improved Transformation between HILL and Metric Conditional Pseudoentropy

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Abstract. HILL Entropy and Metric Entropy are generalizations of the information-theoretic notion of min-entropy to the setting where an adversary is computationally bounded.

The notion of HILL Entropy appeared in the breakthrough construction of a PRG from any one-way function, and has become the most important and most widely used definition of computational entropy. In turn, Metric Entropy which is defined as a relaxation of HILL Entropy, has been proven to be much easier to handle, in particular in the context of computational generalizations of the Dense Model Theorem.

Fortunately, Metric Entropy can be converted, with some loss in quality, to HILL Entropy as shown by Barak, Shaltiel and Wigderson.

In this paper we improve their result, slightly reducing the loss in quality of entropy. Interestingly, our bound is independent of size of the probability space in comparison to the result of Barak et al. Our approach is based on the theory of convex approximation in L^p -spaces.

1 Introduction

1.1 Computational Entropy

THE IDEA OF COMPUTATIONAL ENTROPY. The notion of entropy, as a measure of randomness, is a fundamental concept in information-theory. The need for computational versions of entropy comes from the fact that security definitions based on classical information theoretic entropy notions are quite often too strong for “practical” purposes, where resources of adversaries are limited. The distribution which is not perfectly random might look random from the computational point of view, when finding the real difference is simply inefficient. The metrics used to quantify the amount and quality of pseudorandomness are commonly called computational entropies.

HILL ENTROPY AND METRIC ENTROPY. The most popular approach of extending information-theoretic notions of entropy into computational case, is based on the notion of computational indistinguishability. We discuss it briefly below.

Given a class of boolean functions \mathcal{D} and a parameter ϵ we say that two n -bit random variables X and Y are (\mathcal{D}, ϵ) -indistinguishable if no function D from the class \mathcal{D} can distinguish X and Y with the advantage better than ϵ . Formally

$$\mathbf{E} D(X) - \mathbf{E} D(Y) \leq \epsilon \quad \text{for all } D \in \mathcal{D}$$

If \mathcal{D} is the class of all circuits of size at most t we slightly abbreviate this notation and say that X and Y are (s, ϵ) indistinguishable.

In theoretical computer science and especially in cryptography the most popular notion of entropy is the min-entropy (in contrast to information-theory where one uses extensively the Shannon entropy), because it measures randomness in terms of “hardness” of predictability. The min entropy of X given (possibly) Z is at least 2^{-k} if one cannot predict X given $Z = z$, on average¹ over z , better than with probability 2^{-k} . Formally, for X and Z one defines the average min-entropy [4] of X given Z as follows

$$\tilde{\mathbf{H}}_{\infty}(X|Z) \geq k \text{ iff } \mathbf{E}_{z \leftarrow Z} \left[\max_x \Pr[X = x|Z = z] \right] \leq 2^{-k}.$$

Based on the concept of indistinguishability and min-entropy, one defines computational HILL entropy [10] of X as the maximum amount of min-entropy in a random variable Y (taking values in the same set X) which is indistinguishable from X . This idea was extended to the conditional case (the presence of side information) by [11]. We can state the definition as follows:

$$\mathbf{H}_{\infty}^{\text{HILL},(s,\epsilon)}(X|Z) \geq k \text{ if and only if there exists } Y \text{ jointly distributed with } Z \text{ of average min-entropy (given } Z) \text{ at least } k \text{ such that } |\mathbf{E} D(X, Z) - \mathbf{E} D(Y, Z)| \leq \epsilon \text{ for all circuits } D \text{ of size at most } s.$$

Note that this captures the standard notion of pseudorandom distribution (for $k = n$). By *switching the order of quantifiers* and restricting to deterministic circuits one obtains a slightly weaker version, called computational metric entropy [1, 5]

$$\mathbf{H}_{\infty}^{\text{M,det}[0,1],(s,\epsilon)}(X|Z) \geq k \text{ iff for every } \textit{deterministic} [0, 1]\text{-valued circuits } D \text{ of size at most } s \text{ there exists } Y \text{ jointly distributed with } Z \text{ of average min-entropy (given } Z) \text{ at least } k \text{ such that } |\mathbf{E} D(X, Z) - \mathbf{E} D(Y, Z)| \leq \epsilon.$$

In both definitions the parameters s, ϵ quantify the quality of pseudorandomness: the bigger s and the smaller ϵ , the higher quality is. Metric entropy is known to be equivalent to HILL entropy with the same amount and some loss in quality parameters [1, 2]. There are very good reasons to introduce and study metric-entropy: quite often it is much easier to prove a statement for metric-entropy and then pass to the HILL version. Actually, this strategy is unavoidable for the standard proof technique which uses the min-max theorem to switch the order of players in a game. Therefore, many facts on HILL entropy uses metric entropy explicitly or implicitly [1, 2, 5, 7, 14, 17]. Perhaps the most spectacular example is the efficient version of the Dense Model Theorem [5, 14], being the key ingredient of the famous result of Tao and Ziegler on primes in arithmetic progressions [16]. The efficient version, which found many interesting applications in complexity

¹ Sometimes one uses the stronger notion, called the worst-case min-entropy, when we require the same upper bound on guessing probability for every auxiliary input z , not only on average.

theory, was originally proved using the idea of metric computational entropy in [14] and independently in [5]. A much simpler proof with significant improvements in quality was given in [6].

CONVERSIONS BETWEEN HILL AND METRIC ENTROPY. The following result states that metric and HILL computational entropy are equivalent up to some loss in quality

Theorem 1 (Transformation between Metric and HILL Computational Entropy [1]). *Let X and Z be, respectively, n -bit and m -bit correlated random variables. Then*

$$\mathbf{H}^{\text{HILL},(s',\epsilon')} (X|Z) \geq \mathbf{H}^{\text{M,det}[0,1],(s,\epsilon)} (X|Z)$$

where $s' = \mathcal{O}(s \cdot \delta^2 / (n + m))$ and $\epsilon' = \epsilon + \delta$ for arbitrary $\delta \in (0, 1)$.

Remark 1. Since we have $\mathbf{H}^{\text{HILL},(s,\epsilon)} (X|Z) \leq \mathbf{H}^{\text{M,det}[0,1],(s,\epsilon)} (X|Z)$, the conversion in the other direction is lossless.

1.2 Our Contribution

OUR RESULT. We improve Theorem 1 of Barak, Shaltiel and Wigderson in the following way:

Theorem 2 (Dimension-independent transformation between metric and HILL entropy). *For any n -bit random variable X and a correlated random variable Z we have*

$$\mathbf{H}^{\text{HILL},(s',\epsilon')} (X|Z) \geq \mathbf{H}^{\text{M,det}[0,1],(s,\epsilon)} (X|Z)$$

where $\delta \in (0, 1)$ is an arbitrary parameter, $s' = \mathcal{O}(s \cdot \delta^2 / (\Delta + 1))$, $\epsilon' = \epsilon + \delta$ and $\Delta = n - k$.

In comparison to Theorem 1 we replace the factor $n + m$ by $\Delta + 1$. Our result shows that the conversion does not depend on the dimension of the domain of X and Z but *only* on the entropy deficiency Δ . While this does not offer significant improvement in the asymptotic setting, it might be of some interest in case when m is much longer than n (see for instance equivalence between HILL and unpredictability entropy of X given Z for short X [17]) or when the deficiency Δ is very small. We also remark that our result automatically improves the best known parameters for the efficient dense model theorem by the factor of n .

OUR TECHNIQUES. Our results might be interesting because of the novel proof technique: instead of using Chernoff Bounds for approximating convex hulls with *uniformly* small error as in [1], we show that it is enough to do the approximation with respect to the p -th norm induced by some appropriately chosen measure, and optimize the value of p . There is a lot of research focused on achieving better rates of convex approximations in L^p -spaces for some restricted class of functions. In case of the metric-to-HILL transformation (or similar result) it might be possible to obtain some further improvements for restricting classes of adversaries.

1.3 Organization of the Paper

In Section 2 we explain basic notions and provide necessary definitions. The proof of our main technical result together with an improved Metric-to-HILL transformation appears in Section 3. In Section 4 we demonstrate a simple application: a slight improvement over the best known parameters for the Dense Model Theorem.

2 Preliminaries

PROBABILITIES, MEASURES AND INTEGRALS. By μ_X or \mathbf{P}_X we denote the probability mass function (distribution) of X , that is $\mu_X(x) = \mathbf{P}_X(x) = \Pr[X = x]$ for all x . A measure ν on a finite set Ω is a function $\mu : \Omega \rightarrow \mathbb{R}^+ \cup \{0\}$. For notation convenience, we use the signs of sums and integrals interchangeably. The integral of a function D on E with respect to a measure ν is defined as $\int_E D d\nu = \sum_{x \in E} D(x)\nu(x)$. For the integral over the entire domain we omit the subscript E .

L^p SPACES. Given a finite set Ω and a measure μ on Ω one defines the p -th norm of a real-valued function D defined on Ω as $\|D\|_p = \int_\Omega D d\mu$

CONVEX COMBINATIONS. Given a set of real-valued functions \mathcal{C} defined on the same domain, by $\text{conv}_t(\mathcal{C})$ we denote the set of all convex combinations of length at most t of members of \mathcal{C} . That is,

$$\mathcal{C}_t = \left\{ \sum_{i=1}^t \alpha_i D_i : \sum_{i=1}^t \alpha_i = 1, \alpha_i \geq 0 \text{ for } i = 1, \dots, t, D_i \in \mathcal{C} \text{ for } i = 1, \dots, t \right\}$$

COMPUTATIONAL ENTROPY NOTIONS.

Definition 1 (Conditional HILL Pseudoentropy [11]). *Let X, Z be a joint distribution with the following property: there exists Y of conditional min-entropy at least k given Z such that for all circuits D of size at most s we have $|\mathbf{E}D(X, Z) - \mathbf{E}D(Y, Z)| \leq \epsilon$. Then we say that X given Z has k bits of HILL min-entropy of quality (s, ϵ) and denote by $\mathbf{H}_\infty^{\text{HILL}, (s, \epsilon)}(X|Z) \geq k$.*

Remark 2 (HILL entropy against different circuits classes). For conditional HILL entropy all kinds of circuits: deterministic boolean, deterministic real valued and randomized boolean (for the same size s), are equivalent [6].

Definition 2 (Conditional Metric Pseudoentropy [5]). *Let X, Z be a joint distribution with the following property: for every deterministic boolean (respectively: deterministic real valued or boolean randomized) circuit D of size at most s there exists Y of (conditional min entropy at least k given Z such that $|\mathbf{E}D(X, Z; Y, Z) - \mathbf{E}D(Y, Z)| \leq \epsilon$. Then we say that X given Z has k bits of deterministic (respectively: deterministic real valued or boolean randomized) metric min-entropy of quality (s, ϵ) and denote by $\mathbf{H}_\infty^{\text{M}, \text{det}\{0,1\}, (s, \epsilon)}(X|Z)$ (respectively: $\mathbf{H}_\infty^{\text{M}, \text{det}[0,1], (s, \epsilon)}(X|Z)$ and $\mathbf{H}_\infty^{\text{M}, \text{rand}\{0,1\}, (s, \epsilon)}(X|Z)$).*

3 Main Result

In this section we prove our main technical result which immediately implies Theorem 2.

Lemma 1 (Approximating long convex combinations with respect to high-min-entropy distributions.). *Let X be an n -bit random variable, be Z be a correlated m -bit random variable, and let \mathcal{C} be a class of $[0, 1]$ -valued function on $\{0, 1\}^n \times \{0, 1\}^m$. Let $D \in \text{conv}(\mathcal{C})$. Then for $\ell = 49(n + 1 - k)/\delta^2$ there exists $D_\ell \in \text{conv}_\ell(\mathcal{C})$ such that*

$$\mathbf{E} |D(X) - D_\ell(X)| \leq \delta \tag{1}$$

and simultaneously

$$\mathbf{E} |D(X) - D_\ell(Y)| \leq \delta \tag{2}$$

for every distribution Y jointly distributed with Z such that $\mathbf{H}_\infty(Y|Z) \geq k$.

Corollary 1. *Lemma 1 implies Theorem 2*

Proof (of Corollary 1). If $\mathbf{H}_\infty^{\text{HILL},(s',\epsilon')}(X|Z) < k$ then for every Y satisfying $\tilde{\mathbf{H}}_\infty(Y|Z) \geq k$ we find D of size at most s' such that $|\mathbf{E} D(X, Z) - \mathbf{E} D(Y, Z)| \geq \epsilon'$. Replacing D by D^c of necessary we can assume that $\mathbf{E} D(X, Z) - \mathbf{E} D(Y, Z) \geq \epsilon$ for some D of size $s' + 1$. By applying the min-max theorem we get that there exists a convex combination D' of circuits of size at most $s' + 1$ such that

$$\mathbf{E} D(X, Z) - \mathbf{E} D(Y, Z) \geq \epsilon' \quad \forall Y : \tilde{\mathbf{H}}_\infty(Y|Z) \geq k$$

That combination might be very long. But applying Lemma 1 we can approximate it by a combination D' of at most $\mathcal{O}((n + 1 - k)/\delta^2)$ circuits of size $s' + 1$ in such a way that the expectations with respect to X, Z and Y, Z differs at most by $\delta/2$. This way we obtain

$$\mathbf{E} D'(X, Z) - \mathbf{E} D'(Y, Z) \geq \epsilon' - 2 \cdot \delta/2 \quad \forall Y : \tilde{\mathbf{H}}_\infty(Y|Z) \geq k$$

which finishes the proof. □

Now we prove our main approximation result

Proof (of Lemma 1). Consider the space of all functions on $\{0, 1\}^{n+m}$. We start by the following trivial observation

Claim 1. It suffices to show that for some $D' \in \text{conv}_\ell(\mathcal{C})$ we have $\int |D - D'| \cdot d(\mu_X + \mu_Y) \leq \delta$ for all Y such that $\tilde{\mathbf{H}}_\infty(Y|Z) \geq k$.

By applying the Hölder Inequality, we immediately get

Claim 2. For every functions D, D' and every $p, q > 1$ such that $\frac{1}{p} + \frac{1}{q} = 1$ we have

$$\int |D - D'| \cdot d(\mu_X + \mu_Y) \leq \|D - D'\|_p \cdot \left\| \frac{\mu_{X,Z} + \mu_{Y,Z}}{\mu} \right\|_q \tag{3}$$

Now we give estimates on both factors on the right hand side of Equation (3).

Claim 3. If $q \in [1, 2]$ then for any Y such that $\tilde{\mathbf{H}}_\infty(Y|Z) \geq k$ we have

$$\left\| \frac{\mu_{X,Z} + \mu_{Y,Z}}{\mu} \right\|_q \leq \left(2^q + 2^{(q-1)(n+1-k)} \right)^{1/q} \quad (4)$$

Proof (Of Claim 3). Recall the well-known inequality

Proposition 1. *If $a, b > 0$ and $q \geq 1$ then $(a + b)^q \leq 2^{q-1}(a^q + b^q)$.*

From Proposition 1 it follows now that

$$\left\| \frac{\mu_{X,Z} + \mu_{Y,Z}}{\mu} \right\|_q \leq 2^{q-1} \left(\left\| \frac{\mu_{X,Z}}{\mu} \right\|_q + \left\| \frac{\mu_{Y,Z}}{\mu} \right\|_q \right) \quad (5)$$

We shall estimate two terms in Equation (4) separately. Since $\mu_{X,Z}(x, z) < \mu_{X,Z}(x, z) + \mu_{U,Z}(x, z) = \mu(x, z)$ for all x, z we have

$$\left\| \frac{\mu_{X,Z}}{\mu} \right\|_q < \int 1 d\mu = 2 \quad (6)$$

To bound the second term note that the functional $\mu_{Y,Z} \rightarrow \left\| \frac{\mu_{X,Z} + \mu_{Y,Z}}{\mu} \right\|_q$ is convex as a function of $\mu_{Y,Z}$ (being a composition of an affine function and the p -th norm). Therefore, the maximum among all distributions Y, Z satisfying $\tilde{\mathbf{H}}_\infty(Y|Z) \geq k$, which form a convex set, is attained at an extreme point. This means that the maximum is attained for a distribution (Y^*, Z) such that the distribution $Y^*|_{Z=z}$ is flat for every z and the conditional min-entropy of Y given Z is exactly k . Since $\mu(x, z) = \mu_U(x)\mu_Z(z)$ and $\mu_{Y^*,Z}(x, z) = \mu_{Y^*|_{Z=z}}(x)\mu_Z(z)$ we obtain

$$\begin{aligned} \left\| \frac{\mu_{Y,Z}}{\mu} \right\|_q^q &\leq \int \left(\frac{\mu_{Y^*,Z}}{\mu} \right)^q d\mu \\ &= \int \left(\int \left(\frac{\mu_{Y^*|_{Z=z}}}{\mu_U} \right)^q d\mu_U \right) d\mu_Z \\ &= \int \left(2^{(q-1)(n - \mathbf{H}_\infty(Y^*|Z=z))} \right) d\mu_Z \\ &= 2^{(q-1)n} \int 2^{-(q-1)\mathbf{H}_\infty(Y^*|Z=z)} d\mu_Z \end{aligned}$$

By applying the Jensen Inequality to the function $u \rightarrow u^{q-1}$ (which is concave by the assumption on q) we get

$$\begin{aligned} \left\| \frac{\mu_{Y,Z}}{\mu} \right\|_q^q &\leq 2^{(q-1)n} \left(\int 2^{-\mathbf{H}_\infty(Y^*|Z=z)} d\mu_Z \right)^{q-1} \\ &\leq 2^{(q-1)n} \left(2^{-\tilde{\mathbf{H}}_\infty(Y|Z)} \right)^{q-1} = 2^{(q-1)(n-k)} \end{aligned} \quad (7)$$

Plugin Equation (7) and Equation (6) into Equation (5) yields

$$\left\| \frac{\mu_{X,Z} + \mu_{Y,Z}}{\mu} \right\|_q^q \leq 2^{q-1} \left(2 + 2^{(q-1)(n-k)} \right) = 2^q + 2^{(q-1)(n+1-k)}.$$

and Equation (4) follows. □

Claim 4. Suppose that $p \geq 2$. Then for any $D \in \text{conv}(\mathcal{C})$ and $\ell \geq 1$ there exists $D_\ell \in \text{conv}_\ell(D)$ such that $\|D - D_\ell\|_p < 1.74\sqrt{p/\ell}$.

Proof. The proof relies on the following approximation result on rates of convex approximation, which generalizes the famous Maurey-Johnes-Barron Theorem.

Lemma 2 (Convex approximation in L^p spaces [3]). *Let E be an L^p space with $1 \leq p < +\infty$. Suppose that $S \subset E$, $f \in \text{conv}(S)$ and let $K > 0$ be such that for all $g \in S$ we have $\|g - f\|_p \leq K$. Then for any ℓ we have*

$$\min_{s \in \text{conv}_\ell(S)} \|f - s\|_p \leq \frac{KC_p}{\ell^{1-\frac{1}{t}}}$$

where $t = \min(2, p)$ and $C_p = 1$ if $1 \leq p \leq 2$, $C_p = \sqrt{2}[\Gamma((p+1)/2)/\sqrt{\pi}]^{1/p}$ for $2 < p < +\infty$.

Remark 3. The constant C_p can be estimated using the following approximation for the gamma function [12], valid for $x \geq 1$:

$$\sqrt{\pi}(x/e)^x \sqrt{2x + 0.33} < \Gamma(x + 1) < \sqrt{\pi}(x/e)^x \sqrt{2x + 0.36}$$

From this we find that $C_p < 0.87\sqrt{p}$ for all $p > 2$.

The claim follows by setting E to be the space of $[0, 1]$ -valued functions on $\{0, 1\}^n \times \{0, 1\}^m$ and $K = \int 1d\mu = 2$. □

By Claim 3 and Claim 4 combined with Claim 2 and Claim 1 it suffices to find $p \geq 2$ (which automatically ensures $q \in [1, 2]$) and ℓ such that

$$1.74\sqrt{p/\ell} \cdot \left(2^q + 2^{(q-1)(n+1-k)} \right)^{1/q} \leq \delta.$$

If $k \geq n-1$ then we put $p = q = 2$. Then it suffices to ensure that $1.74\sqrt{2/\ell}(2^2 + 2^2)^{1/2} \leq \delta$ which is equivalent to $6.96\sqrt{\ell} \leq \delta$. Suppose that $k \leq n-1$. By the inequality $(a+b)^r \leq a^r + b^r$ valid for $a, b > 0$ and $0 < r \leq 1$, we see that it suffices if $1.74\sqrt{p/\ell} (2 + 2^{(n+1-k)/p}) \leq \delta$. For $p = n+1-k$ we obtain $6.96\sqrt{\ell} \leq \delta$. This finishes the proof. □

4 Application to the Dense Model Theorem

DENSE MODEL THEOREM. Given a pair of two distributions W and V over the same finite domain we say that W is δ -dense in V if and only if $\Pr[W = x] \leq \Pr[V = x]/\delta^2$. The dense model theorem [16], specialized to the boolean case, can be formulated as follows:

Theorem 3 (Dense Model Theorem.) *Let \mathcal{D}' be a class of n -bit boolean functions, R be uniform over $\{0, 1\}^n$, X be an n -bit random variable and let X' be δ -dense in X . If X and R are (\mathcal{D}, ϵ) -indistinguishable then there exists a distribution R' which is δ -dense in R such that X' and R' are $(\mathcal{D}', \epsilon')$ -indistinguishable, where $\epsilon' = (\epsilon/\delta)^{\mathcal{O}(1)}$ and \mathcal{D} consists of all functions of the form $g(D_1, \dots, D_\ell)$ where $D_i \in \mathcal{D}'$, $\ell = \text{poly}(1/\delta, 1/\epsilon)$ and g is some function.*

Informally, this statement reads as follows: if a distribution X' is dense in a pseudorandom distribution X , then X' must be indistinguishable from a distribution dense in the uniform distribution. Note that the indistinguishability parameters for X' are worse than for X : to achieve $(\mathcal{D}', \epsilon')$ -indistinguishability we need to start with ϵ smaller than ϵ' and a class \mathcal{D} sufficiently more complicated than \mathcal{D}' . Note also that for the statement to be computationally meaningful we need g to be efficient.

APPLICATIONS OF THE DENSE MODEL THEOREM. Efficient versions of the Dense Model Theorem have found applications in differential privacy [13], pseudoentropy and leakage-resilient cryptography [2, 5], graph decompositions [14], and further applications in additive combinatorics [9]. We refer the reader to [15] for a survey.

COMPARISON OF DIFFERENT FORMULATIONS. Below we compare the different versions of the Dense Model Theorem. Note that an equivalent statement in language of pseudoentropy was given in [5].

Table 1: The quantitative comparison of different versions of the Dense Model Theorem

Author	Function g	ℓ as complexity of \mathcal{D}' w.r.t \mathcal{D}	ϵ' vs ϵ
[16]	Inefficient	$\ell = \text{poly}(1/(\epsilon/\delta), \log(1/\delta))$	$\epsilon' = \mathcal{O}(\delta/\epsilon)$
[8, 14]	Linear threshold	$\text{poly}(1/(\epsilon/\delta), \log(1/\delta))$	$\epsilon' = \mathcal{O}(\delta/\epsilon)$
[6], [5]	Linear threshold	$\ell = \mathcal{O}(n/(\epsilon/\delta)^2)$	$\epsilon' = \mathcal{O}(\epsilon/\delta)$
This paper	Linear threshold	$\ell = \mathcal{O}(\log(1/\delta)/(\epsilon/\delta)^2)$	$\epsilon' = \mathcal{O}(\epsilon/\delta)$

Below we show how to derive from our Lemma 1 a version of the Dense Model Theorem where n was replaced by $\log(1/\delta)$, which is typically much smaller.

Corollary 2. *Dense Model Theorem (Theorem 3) holds with $\epsilon' = \mathcal{O}(\epsilon/\delta)$, g being a linear threshold and $\ell = \mathcal{O}(\log(1/\delta)/(\epsilon/\delta)^2)$.*

² The term “ δ -dense” comes from the fact that V can be written as a convex combination of W with weight δ and some other distribution with weight $1 - \delta$

Proof. We show how to reduce the formulation of the Dense Model Theorem to the statement about HILL entropy. We start by the following observation:

Claim 5. X' is δ -dense in X if and only if X' can be written as $X|A$ for some event A of probability δ .

Proof. of Claim Consider a random variable $A \in \{0, 1\}$ jointly distributed with X as follows: $\Pr[X = x, A = 1] = \delta \Pr[X']$. By the assumption on X and X' we have $\Pr[X = x, A = 1] \leq 1$ and thus this distribution is well defined, in particular we have $\Pr[A = 1] = \delta$ and $\Pr[X|A = 1] = \Pr[X']$. In the other hand if we have $X' \stackrel{d}{=} X|A$ then $\Pr[X' = x] = \Pr[X = x, A] / \Pr[A] \leq \Pr[X = x] \leq \Pr[X = x] / \Pr[A]$ and hence X' is $\Pr[A]$ -dense in X . \square

The second fact we need is the so called leakage lemma for metric-entropy

Lemma 3 ([7], reformulated). *Let X be a random variable, A be an event of probability δ , and let \mathcal{D} be a class of $[0, 1]$ -valued functions. Suppose that there exists D such that $\mathbf{E} D(X|A) - \mathbf{E} D(Y) \geq \epsilon'$ for all Y of min-entropy at least $k - \log(1/\Pr[A])$ and $\epsilon' = \epsilon/\Pr[A]$. Then there exists a function D' being a threshold of some $D \in \mathcal{D}$ (or its complement) such that $\mathbf{E} D'(X) - \mathbf{E} D'(Y) \geq \epsilon$.*

The name ‘‘leakage lemma’’ is due to the fact that this implies $\mathbf{H}_\infty^{\text{M, det}[0,1],s,\epsilon}(X|A) \geq \mathbf{H}_\infty^{\text{M, D},s'\epsilon/\Pr[A]}(X) - \log(1/\Pr[A])$ for $s' \approx s$. Now we are ready to give the proof. Suppose contrary, that the Dense Model Theorem is not true with the claimed parameters. Then for some event A of probability δ , some ϵ' and every distribution Y of min-entropy $n - \log(1/\delta)$ (which is equivalent to be δ -dense in the uniform distribution) there exists $D \in \mathcal{D}$ or $D \in \mathbf{1} - D \in \mathcal{D}$ such that

$$\mathbf{E} D(X|A) - \mathbf{E} D(Y) \geq \epsilon'$$

By applying a min-max theorem we get that there exists a long convex combination \bar{D} of functions from $\mathcal{D} \cup (\mathbf{1} - \mathcal{D})$ such that

$$\mathbf{E} \bar{D}(X|A) - \mathbf{E} \bar{D}(Y) \geq \epsilon' \quad \forall Y : \mathbf{H}_\infty(Y) \geq n - \log(1/\delta).$$

Now we use our Lemma 1, with the class $\mathcal{D} \cup (\mathbf{1} - \mathcal{D})$ and δ replaced by $\epsilon'/3$ to approximate \bar{D} by a convex combination D' of length $\ell = \mathcal{O}(\log(1/\delta)/\epsilon'^2)$. Then we get

$$\mathbf{E} D'(X|A) - \mathbf{E} D'(Y) \geq \epsilon' \quad \forall Y : \mathbf{H}_\infty(Y) \geq n - \log(1/\delta).$$

Note that D' is a linear threshold of ℓ functions from \mathcal{D} . By Lemma 3 we replace D' by D'' which is again a linear threshold of ℓ functions from \mathcal{D} and satisfies

$$\mathbf{E} D''(X) - \mathbf{E} D''(Y) \geq \epsilon' \quad \forall Y : \mathbf{H}_\infty(Y) \geq n.$$

Hence, we get a contradiction. \square

5 Conclusion

In this paper we improve the transformation between conditional Metric and HILL entropy by replacing the dimension factor by the entropy deficiency. This result immediately translates into a slightly improved version of the Dense Model Theorem. An interesting question is the problem of finding complexity lower bounds for that transformation.

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