Semantic features of processing hybrid dynamic workflows of design

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Abstract. The article examines the semantic peculiarities of grammatical processing models of visual languages like RC ASCON-Volga, BPMN and eEPC as denotative and significative semantics. It is offered author's structure of the denotation and significata. Methods of control, analysis of qualitative and quantitative characteristics of workflows, transformation and interpretation of workflows are proposed by authors. A temporary automatic grammar of RC ASCON-Volga, BPMN and UML AD visual languages is proposed by authors for semantic processing of hybrid dynamic workflows, as well as for analysis and control of denotative and significative semantic errors.

1. Introduction

The paradigm associated with the hybrid dynamic nature of their nature is increasingly dominating in the creation of project workflows. Hybridity is defined not only as the development of models using different diagram bases (for example, UML AD [1], BPMN [2], IDEFO [3]), but also as the composition of orchestration and choreography [4, 5] in the form of an ensemble. Dynamism is determined by the need for immediate response to emerging production requests and contains the concept of «time», so the elimination of errors in the flow of work is a significant scientific and technical problem. Under treatment refers to the analysis, control, transformation, and interpretation workflows, and analysis and control diagrammatically models of the error associated with denotative and significative the semantics. Denotative semantics of diagram models is represented by a sequence of temporal words of the formal automaton language in the form of traces and defines antonymy, synonymy of these words in order to identify errors in the events of diagram models. The significative semantics of diagram models reveals the relations of isomorphism, homomorphism of these traces for the purpose of localization of structural errors in diagram models, and also for their subsequent transformation. Changing the design of the diagram models is possible with the identified synonyms, antonyms of graphic words, isomorphic traces and the possibility of combining such traces into a single track. A necessary condition for the transformation of the flow of design work is the presence of a semantic error. Detection of such errors is possible with the help of step-by-step automated interpretation (tracing) of the project work flow in debug mode. Automata-based grammars allow you to present a diagram model of the flow of design work in the form of a graph with vertices, arcs and in a visual form to represent the process of interpreting the flow of design work as a system of transitions. The methods of analysis can be used to study the qualitative and quantitative characteristics of project work flows. Under qualitative characteristics refers to the logical-algebraic correctness of workflows, formalized using graph theory, networks, workflows, matrix matching, graphical modeling languages, including Unified Model Language, Business Process Management Notation, IDEFO and eEPC, etc., and also the evolutionary approach, logic statements, etc. Quantitative characteristics represent the effectiveness of the execution of the workflow in the

parameters, such as average service time, the utilization rate of production capacity (downtime), etc. The efficiency of workflows is evaluated using simulation modeling (Petri nets), Markov chains and Queuing theory (Queuing systems).

In this paper, the authors developed a temporary automatic grammar of visual languages of RC ASKON-Volga, BPMN and eEPC, as well as denotative and significative semantics of diagram models of visual languages as a general structure for semantic processing of diagram models of hybrid dynamic design workflows. Processing will reduce the time, improve the success and quality of charting models. The mathematical apparatus of processing of diagram models of hybrid dynamic flows of design work allows to simulate the process of workflows in the form of a finite state machine. The work contains an introduction, the author's description of denotative and significative semantics of workflows in the visual languages of RC ASCON-Volga, BPMN and eEPC. The review of qualitative and quantitative methods for estimating the characteristics of workflows presents mathematical tools for the analysis, control and modeling of workflows. In the section of the Temporal automaton RVTI-grammar author presents automata-based temporal grammar for visual language RC ASKON-Volga, BPMN and UML AD. In the section Transformation the author's temporal automatic grammar is offered. In conclusion, briefly concludes the work and identifies future directions of work.

2. Related work

The authors investigate some works that consider the specification of document flow, verification and translation. Several papers focused on the definition of formal semantics and validation methods for workflows using Petri nets, process algebra, abstract state machine, see for example [6-16]. In [12, 13], Decker and Weske propose a Petri net-based formalism for determining choreographies, properties as realizability and local applicability, and a method for verifying these two properties. However, they consider only synchronous communication and does not explore the association with languages modeling of interaction of a high-level BPMN. Bultan and Fu [17] determine a sufficient condition for analyz-ing the feasibility of choreographies defined using UML collaboration diagrams (CD). In [18], Salaün and Bultan modify and extend this work with the feasibility analysis method by adding a synchronization message among peers. This method controls the realizability of CDs for bounded asynchronous communication. The feasibility problem for Message sequence diagrams (MSCs) has also been studied (e.g. [19, 20]). In [20], the authors offer bounded MSCS graphs which are bound-ed by BPMN 2.0 because branching and looping behavior are not supported by CDs and MSCs (there is no selection in CDs, there are no some looping behaviors in MSCs, and only Selfloops in CDs). In [21] BPMN behavior is studied from the semantic point of view and several BPMN patterns are proposed. This work is not theoretically justified and is not complete, it discusses only some of the laws. Lohmann and Wolf [22] propose to analyze existing patterns and control them with compatible patterns. In [23], the authors focused on the translation of BPMN into the algebra of processes for the analysis of choreography using model checking and equivalence. The main limitation of these methods is that they do not work when there are different types of diagrams at the same time, which means that in some cases the input diagrams cannot be analyzed. There are the following paradigms of analysis and control of quality characteristics of work flows: model checking; The model checking approach is equivalence check; deductive verification (Prolog language). intended for the analysis, control of workflows by means of formal check of whether the given logical formula is executed on the given structure (whether the given logical formula f will be true for the given system of transitions M, i.e. whether M will be model f). The main disadvantage of the campaign is the study of the model, not the system itself, so the question arises about the adequacy of the model to the system, and the complexity of the solution of the above problems is exponential. Deductive verification involves checking the correctness of the workflow, which is reduced to proving theorems in a suitable logical system with the help of axioms and inference rules (for example, with the help of the Prolog language, automatic grammars, etc.). This very complex procedure can not be fully automated, it requires the participation of a person acting on the basis of assumptions and guesses, using intuition in the construction of invariants and non-trivial choice of alternatives. The equivalence test determines the equivalence of formal models of specification, implementation and execution (behavior) of workflows based on the algebra of processes (Calculus of interacting systems). Simulation modeling is a flexible approach to analysis and is applied almost always to the analysis of workflows, which is reduced to determining the path in the reachability graph, taking into account the probability of distribution. Multiple execution of workflows using a computer provides «ease» of understanding of the functional people who do not have mathematical training. Visual representation and analysis of workflows is available in many tools for modeling workflows. Usually use Petri nets in the modeling and analyzed the following properties: reachability (reachability) - which sets out that the final state of the system is reached when any sequence of transitions from positions i. This property also implies that upon reaching the final position of the network there are no chips in the intermediate positions; security (safety), establishes that the processes do not exist hangs (deadlocks), looping dead ends; vitality (liveness) - specifies that the system does not contain unnecessary items that will never be fulfilled. The lack of liveliness means either redundancy of the business process in the designed system, or indicates the possibility of loops, deadlocks, locks. Flow rate, transmission rate, waiting time, service time, and capacity utilization can be calculated using queue theory. If we are interested in the formation of a separate queue to multiple resources of the same type, it is necessary to confine the system with a single queue. When considering the entire flow, Queuing systems are best used. The main models used in Queuing theory are single-and multi-channel Queuing systems (QSOS). The most simple model of the workflow to determine complexity of the corresponding phase can be obtained if we accept the assumption about the absence of consequences in the process, meaning that the next job in the flow depends only on the current state and does not depend on previous States. In this case, the flow of work becomes a Markov process determined by a variety of inherent conditions and the matrix of transition probabilities, and a probability distribution of states in the initial moment of time.

3. Denotative and significative semantics of diagram models of visual languages of RC ASCON-Volga, BPMN and eEPC

Denotative semantics [24-26] of any visual language is represented by denotates in the form of graphical objects (words). The denotate of a word in the theory of visual languages is understood as an instance of a class with specific values of properties characterizing the belonging of a word to a subject. The authors have developed a general structure of the denotation and significate graphic words. The general structure of the graphical class instance of a word is displayed in listing 1.

Listing 1. Generalized structure of the graphic denotation of the word.

```
The class name class=start
beginning
property 1=value 1
property 2=value 2
property n=value n
end
```

The structural units of the parameters (properties) of the graphical word represent the signature of the word, and the properties themselves are combined into a class (listing 2).

Listing 2. Generalized structure of significata graphic words.

<u>Class name: text</u> <u>beginning</u> <u>property 1: type 1</u> <u>property 2: type 2</u> <u>property n: type n</u> end

```
The description of denotates and significations in the set-theoretic language has the following form.
```

NameOfDenotate =

(*ValueOfProperty_1*, *ValueOfProperty_2*, *ValueOfProperty_3*, ..., *ValueOfProperty_N*), (1)

where *NameOfDenotate* is the name of the denotation (class instance) the graphic word; *ValueOfProperty_1* is the value of the first property of the graphic word; *ValueOfProperty_2* is the value of the second property of the graphic word; *ValueOfProperty_3* is the value of the third property of the graphic word; *ValueOfProperty_N* is the value of n-th property of a graphical word.

where *Significatum* is the name of significata (class) graphic words; *Property1* is structure of the first property of the graphic word; *Property2* is structure of the second property of the graphic word; *Property3* is structure of the third property of the graphic word; *PropertyN* is structure of n-th property of a graphical word.

The difference between the significate and the denotate is that the denotate is an instance of the significate, i.e. the properties (structure) of the denotate have specific values. Further in tables 1, 2, 3 denotative and significative semantics of grammatical models of hybrid dynamic streams of design works of visual languages of RC ASKON Volga, BPMN, eEPC are presented [27-35].

Graphic word	Concept	Class	Class properties	The values of class properties
	A collapsed subprocess that can be called multiple times. Has only one inbound link of type «go to procedure»	Procedure	Input Algorithm Output	Input=work thread Algorithm=ishodnyh Output=Potocari
	Collapsed subprocess, the action is required to be performed by the user	Task	Input Text of task Output	Input=work thread Textpane=scriptside Output=work thread
	Collapsed subprocess, the implementation of which is required repeatedly	Iteration	Algorithm	Algorithm=source code
	Used in conjunction with «go to procedure» and «procedure» block	Procedure call	Adres call procedure	Adres call procedure=number
	Used in conjunction with «go to procedure» and «procedure» block $% \left({{{\rm{D}}_{{\rm{s}}}}} \right)$	Thread creation	Name Adresie	Name=stream_name Adresie=number
E	The operation performed by the user	No transit	opcode operand address 1 operand address 2	opcode=number operand address 1=number operand address 2=number
A	Automated (automatic) execution of operations	The script (auto operation)	Algorithm	Algorithm=source code
	It has only two outgoing connections. True and False, respectively	Branching	Condition	Condition=source code
	Allows you to connect parts of the chart at different levels of nesting. In fact a connection	Phantom	From level Against the level	Isorena=numerowana Karouny=numerowana
Er	Used in conjunction with «waiting». Three incoming, one of them «Synchro action», notifying about the event.	Event	Time	Time=number
Se	Used in conjunction with «waiting». Three incoming,	Semaphore	Beginning	Start=number
\bigcirc	one of them «Synchro action», notifying about the beginning and completion of events.	-	Completion	Completion=number
F	Has two outgoing branches, one of them «Synchro action», notifying «Event» on successful completion of the event	Activate	Output	Output=Boolean
Ŵ	It has two outgoing branches, one of them «Synchro action», which monitors the status of the event. Skips the stream only if the event succeeds	1	Duration	Duration=number
\frown	It has two outgoing branches, one of them «Synchro	Increment	With	C=the number
	action», notifying «Semaphore» about the beginning of		On	By=number
	the event execution		Step	Step=number
Dec	It has two outgoing branches, one of them «Synchro	Decrement	From	From=number
\bigcirc	action», notifying «Semaphore» about the completion of		То	Up=number
	the event		Step	Step=number

Table 1. Denotative and significative semantics of the visual language of RC ASCON-Volga.

Graphic	Concept	Class	Class	The values of class
word			properties	properties
	Has no incoming threads	Starting event	Output	Output=work thread
Ŏ	Only one incoming and outgoing stream	Intermediate event	Input Operation	Input=work thread Operation=algorithm
Ø	Can be a trigger	Intermediate event «Message»	Output Input Event Output	Output=work thread Input=work thread Event=algorithm Output=work thread
0	Has no outgoing streams	Final event	Input	Input=work thread
	Incoming stream	Action	Input Procedure	Input=work thread Procedure=algorithm
×	Only one outgoing branch is allowed to flow	Exclusive gateway	Output Input Condition	Output=work thread Input=work thread Condition=algorithm
$\langle 0 \rangle$	It can be only one trigger event	Gateway the Event- based	Output Input Event Output	Output=work thread Input=work thread Event=algorithm Output=work thread
(+)	Activated only if there is a thread on each incoming branch	Parallel gateway	Input 1 Input 2 Input 3 Input s Output	Input 1=work thread Input 2=work stream Input 3=work stream Input=work thread Output=work thread
	Can connect to any flow element by association	Data object	Document	Document=text
	The relationship between the graphical objects	A regular relationship	From To	From=graphical object To=graphical object
٩	Allows you to monitor an invalid sequence of elements	Event-based gateway	From	From=graphical object
	Associative relationship between graphical objects by key	communication Association	To From To	To=graphical object From=graphical object To=graphical object

Table 2. Significative and denotative semantics of the visual language of BPMN.

Table 3. Significative and denotative semantics of the visual language eEPC.

Graphic	Concept	Class	Class	The values of
word			properties	class properties
	It is the fact of accomplishment of something, and not having duration in time, or this time to aspire to zero (or does not matter)	Event	Time	Number
	Execution of a function always ends with the event	Function	Function	The function=algorithm
	Workflow direction	Through a process	From To	From=work thread To=work thread
\bigcirc	The object reflects the various organizational units of the enterprise	Unit	Name	Name=text
XOR	A logical operator that defines the relationship between events and functions within a process. Allows you to describe the branching process	exclusive or	From To	From=work thread To=work thread
v	A logical operator that defines the relationship between events and functions within a process. Allows you to describe the branching process	OR	From To	From=work thread To=work thread
\land	A logical operator that defines the relationship between events and functions within a process. Allows you to describe the branching process	AND	From To	From=work thread To=work thread
	The object reflects the media	Information (Material)	Document	Document=text
	Core business process	Main process	From To	From=graphical object To=graphical object
	Structural and functional element	Component	Name	Name=text
	Area of research	Subject area	Name	Name=text
\sum	A set of simple processes, collected on the same basis and solve the same problem	Process group	Name	Name=text
	The relationship between the graphical objects	Dynamic connection line	From To	From=graphical object To= graphical object

Semantic errors of grammatical models of work flows include the following errors [36]. Synonym mismatch (denotative error). Temporal words of visual language (\tilde{a}_l, t_i) and (\tilde{a}_k, t_i) are synonyms if and only if $\tilde{a}_l \neq \tilde{a}_k, \tilde{a}_l \equiv \tilde{a}_k, t_i < t_j$ and indicated synonymy of the words $as(\tilde{a}_l, t_j) \equiv (\tilde{a}_k, t_j)$. The identical equality of the word determines the similarity (similarity) of the structure and values of denotate features. A mistake is the situation when the name of the denotates of words in two temporal traces of the graphical language are similar, but the values of other features are very different. In practice, this situation is presented as follows: the analysis of the grammatical model of the visual language reveals the structural similarity of words and names of denotates, but the values of other features of denotates of words are different. To present variants of the composition of products under different conditions: in versions, substitutability and interchangeability, in this situation, the implementation of interchangeability of such words in the diagram model of the visual language is a mistake of non-conformity of synonyms. Discrepancy of antonyms (denotative error). Temporal words of visual language (a_l, t_j) and (a_k, t_j) are antonyms if and only if $a_l = \neg a_k, t_i < t_j$ and is denoted by antonyms to words as $(a_l, t_l) \equiv (\neg a_k, t_k)$. Identical to the opposite of the two words defines the similarity (similarity) of the structure and the opposite (inversely) characteristic value of the denotation. Generally, the words «Beginning» and «End» in charting are antonyms of the graphical language. A mistake is the project situation when the name of denotates of words in two temporal traces of graphic language are opposite (inverse), but the values of other signs are very similar. In practice, this situation is presented as follows: when analyzing the diagram model of the visual language, structural similarity of words and inversion of denotate names are revealed, but the values of the other signs of denotate words are similar. In this situation, the interchangeability of such words in the diagram model of the visual language is a mistake of discrepancy of antonyms. Conversionist relations is to bind antonyms diagrammatically models of visual languages that describe the same design situation, but with different roles. Error conversionist relations is significative, i.e. structural (structural), and is defined as the lack of these relations between antonyms diagrammatically models describing the same design situation, but with different roles. The inconsistency of the objects is significatively mistake. Is the absence of a relationship between dependent temporal words.

4. Temporal automata-based RVTI grammar

The temporal automaton RVTI grammar of the language L (G) is called the ordered eight of nonempty sets $G = (V, \Sigma, \tilde{\Sigma}, C, E, R, \tau, r_0)$, where $V = \{v_e, e = \overline{1.L}\}$ is auxiliary alphabet (the alphabet of operations on internal memory, represented by the store or elastic band); $\Sigma = \{a_n, n = \overline{1.T}\}$ is alphabet of graphic symbols (objects); $\tilde{\Sigma} = \left\{ \widetilde{a_n}, n = \overline{1, \tilde{T}} \right\}$ is quasi-terminal alphabet, which is an extension of the terminal alphabet \sum ; $C = \{c, c = c + t_l | \exists t_0 = 0 \rightarrow c = 0\}$ is clock ID (counter); $\tau = \{t_l \in [0; +\infty], l = \overline{1.K}\}$ is a lot of timestamps, and $c \in [t_l; t_{l+1}]; E$ is temporal aspect ratio $\{c \sim t_l\}$, where variable c (ID hours), the ratio $\sim \in \{=, \langle, \leq, \rangle, \geq\}$), describing the condition of the occurrence of an event t_i ; $R = \{r_i, i = \overline{0, I}\}$ is scheme of grammar G (the set of names of products of complexes, each complex r_i consists of a subset P_{ij} products' $r_i = \{P_{ij}, j = \overline{1.J}\}$; $r_0 \in R$ is the axiom of RVTI-grammar (name of the initial complex of products), $r_k \in R$ is the final set of products. Product $P_{ij} \in r_i$ have the form $a_i \xrightarrow{\{W_{\gamma}(\nu_1, \dots, \nu_n) | E\}} r_m$, where $W_{\gamma}(\nu_1, \dots, \nu_n)$ is n-ary ratio, which determines the type of operation on the internal memory, depending on $\gamma = \{1,2,3\}$ (1 – write, 2 – read, 3 – a comparison), $E = \emptyset$ and $c \neg \sim t_l$; (a_l, t_l) is words as a pair of quasi-symbol and timestamp; $r_m \in R$ is name of the successor product complex. The language of this grammar contains words of the form $(\tilde{a_l}, t_l)$ and $E \neq \emptyset$ and $\tilde{a_l}$ and $E = \emptyset$, represents the alignment $\sigma = \{\tilde{a_0}, 0\} \rightarrow \{\tilde{a_l}, t_l\} \lor \tilde{a_l} \rightarrow \tilde{a_l}$ $\{a_k, t_k\}$. In tables 4 and 5 present the temporal grammars for specific language RC ASKON Volga and language BPMN.

Complex-source	Quasi term	The complex receiver The memory operation		
r_{0}, t_{0}	A_0	r ₃ ,t3	Ø/E	
r_l, t_l	return	r_2, t_4	$w_2(b^{4m})$	
r_{2}, t_{2}	vA	r_{1}, t_{1}	$w_l(s^{lm}, t^{4m}), CALL vA/E$	
	vIT	r_1, t_1	$w_{I}(s^{Im},t^{4m}), CALL vIT/E$	
	Ak	<i>r</i> ₄ , <i>t</i> ₄	Ø	
	Akm	<i>r</i> ₅ , <i>t</i> ₅	$w_1(1^{t(1)}, i^{t(2)})/w_2(e^{t(1)})/E$	
	Akm	r{5}, t_{5}	$w_1(inc(m^{t(1)}))/w_3(m^{t(1)} < k^{t(2)} - 1), E$	
	Akme	r ₄ ,t ₄	$w_1(inc(m^{t(1)}))/w_3(m^{t(1)}=k^{t(2)}-1),E$	
	CL	r_{6}, t_{6}	$w_l(t^{4m})$	
	TH	r_{6}, t_{6}	$W_{I}(I^{t(7)}, i^{t(8)}, t^{4m})$	
	SC	r_3, t_3	Ø	
	SCm	<i>r</i> ₅ , <i>t</i> ₅	$w_1(I^{t(3)}, i^{t(4)})/w_2(e^{t(3)}), E$	
	SCm	r{5}, t_{5}	$w_1(inc(m^{t(3)}))/w_3(m^{t(3)} < k^{t(4)} - 1), E$	
	SCme	<i>r</i> ₃ , <i>t</i> ₃	$w_1(inc(m^{t(3)}))/w_3(m^{t(3)}=k^{t(4)}-1),E$	
	С	r_{7}, t_{7}	$w_l(t^{2m})$	
	EV	r_3, t_3	$w_1(O^{t(5)}, O^{t(9)}, O^{t(11)})/w_2(e^{t(5)}), E$	
	S	<i>r</i> ₃ , <i>t</i> ₃	$w_1(O^{t(6)}, O^{t(10)}, O^{t(12)})/w_2(e^{t(6)}), E$	
	F	r_{11}, t_{11}	$w_I(t^{3m})$	
	W	r ₉ ,t ₉	$w_{l}(t^{3m})$	
	IN	r_{11}, t_{11}	$w_{I}(t^{3m})$	
	D	r_{12}, t_{12}	$w_I(t^{3m})$	
r_{3}, t_{3}	rel	r_2, t_2	Ø	
r_4, t_4	no_label	r_{17}, t_{17}	*	
<i>r</i> ₅ , <i>t</i> ₅	labelC	r_{2}, t_{2}	$w_2(b^{2m})$	
r_{6}, t_{6}	prel	r_{13}, t_{13}	Ø	
r_{7}, t_{7}	nrel	r_2, t_2	Ø	
r_8, t_8	PHsp	r_{6}, t_{6}	Ø	
r9,t9	arel	r_{14}, t_{14}	Ø	
r_{10}, t_{10}	PHsa	r9,t9	Ø	
r_{11}, t_{11}	airel	r ₁₅ ,t ₁₅	Ø	
r_{12}, t_{12}	adrel	<i>r</i> ₁₆ , <i>t</i> ₁₆	Ø	
r_{13}, t_{13}	vPR	r_{l},t_{l}	$w_I(s^{lm}), CALL(vPR)/E$	
10. 10	РНер	r8,t8	Ø	
r_{14}, t_{14}	ТНа	r_{2}, t_{2}	$w_1(inc(m^{t(7)}))/w_3(m^{t(7)} < k^{t(8)}), E$	
	PHea	r_{10}, t_{10}	Ø	
	EVa	r_{2}, t_{2}	$w_{l}(I^{t(9)}), w_{2}(b^{3m})$	
	Sa	r_2, t_2	$w_1(1^{t(10)}), w_2(b^{3m})$	
r_{15}, t_{15}	EVa	r_2, t_2	$w_1(inc(m^{t(5)}), 1^{t(11)}), w_2(b^{3m})$	
	Sa	r_2, t_2	$w_1(inc(m^{t(6)}), I^{t(12)}), w_2(b^{3m})$	
r ₁₆ ,t ₁₆	Sa	r_{2}, t_{2}	$w_1(dec(m^{t(6)}), 1^{t(12)}), w_2(b^{3m})$	

 Table 4. Temporal RVTI grammar language RC ASKON Volga.

Complex- source	Quasi term	The complex receiver	The memory operation
r_0	A_0	r_1	Ø
r_{l}	rel	r_3	Ø
r_2	$label_{EG}$	r_3	$W_2(b^{lm},\ b^{\prime(6)})\ W_2(b^{2m},\ b^{\prime(6)})$
	$label_{PG}$	r_3	$W_2(b^{2m}, b^{t(6)})$
r_3	A_i	r_1	Ø
	A_{im}	r_1	Ø
	A_{it}	r_1	$W_{I}(t_{s}^{t(6)}) \\ \emptyset / W_{3}(!e^{lm}, !e^{2m})$
	A_{kl}	r_2	$\emptyset / W_3(!e^{1m}, !e^{2m})$

Complex- source	Quasi term	The complex receiver	The memory operation
	A_k	r_4	Ø
	A	r_1	$W_l(t_s^{t(6)})$
	A_{it}	r_3	$W_l(t_s^{t(6)})$
	EG_c	r_{I}	$W_{l}(t^{1m^{(n-1)}})/W_{3}(k=1)$
	EG	r_2	$W_{l}(I^{t(1)}, k^{t(2)})/W_{3}(e^{t(2)}, k != 1)$
	$_EG$	r_2	$W_1(inc(m^{t(1)})/W_3(m^{t(1)} < k^{t(2)}))$
	EGe	r{I}	$W_{l}(t^{1m^{(n-1)}})/W_{3}(m^{t(1)}=k^{t(2)}, p != 1)$
	$_EG_{me}$	r_{I}	$o/W_3(m^{t(1)}=k^{t(2)}, p=1)$
	PG_{f}	r_{I}	$W_{l}(t^{2m^{(n-1)}})/W_{3}(k=1)$
	PG	r_2	$W_{1}(1^{t(3)}, k^{t(4)})/W_{3}(e^{t(3)}, k!=1)$
	$_PG$	r_2	$W_1(inc(m^{t(3)})/W_3(m^{t(3)} < k^{t(4)}))$
	$_PG_e$	r_{I}	$W_{l}(t^{2m^{(n-1)}})/W_{3}(m^{t(3)}=k^{t(4)}, p!=1)$
	$_PG_{je}$	r_{I}	$W_{l}(t^{2m^{(n-1)}})/W_{3}(m^{t(3)}=k^{t(4)}, p=1)$
r_4	no_label	r_5	*
r_5			

An instance of the diagram model (table 4, table 5) can be used to construct an ontology [27, 30], classes which words the of are (concepts) and have the following form: $Class_0 = (\tilde{a}_k, t_0), \dots, Class_k = (\tilde{a}_k, t_k),$ where a couple (\tilde{a}_i, t_i) is a temporal word. Classes have for example, are represented properties. which, as follows: $Property = \{Name, OrientationTime, ProcessingTime\}, where Name is the name of the field$ (inherited from the name of the notation diagrammatically model); OrientationTime is the start time of the stream; *ProcessingTime* is the duration of the thread.

5. Transformation

Dynamic reconfiguration of business process need to have a mechanism for transformation of diagrams reaching flexibility, improving a functional and an efficiency of enterprise's business process. In work [19-21] the problem of reconfiguration has been researched both theoretical and practical. Authors offer applying the structure transformation of a diagram with help procedures: delete, insert and replace with saving a connection during an interval of time. It is necessary all graphic element have a timed label where we can define time of the transformation. As rule BPMN, eEPC, IDEF0, UML AD etc. graphic elements contain a description (notes in UML AD) which can be define as a timed variable. Let's see an example of UML AD diagram (figure 1).

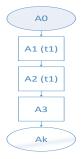


Figure 1. UML AD diagram with t1 timed label.

Graphic elements A1 and A2 have t1 timed labels. This means that a current element will be transform at t1 time with help operations: (1) Insert, (2) Replace, (3) Delete. Reasoning to suppose that only one operation cab be performed at one element. Therefore, timed label is assigned to a tape where an element has their variants: number 1 -Insert, number 2 -Replace, number 3 -delete. Additional information when Insert and Replace saved at extended tape allowing to save both numbers and quasiterms. Additional Insert() function is used for the operation 1 allowing to get needed information from extended tape and form inserted fragment. Operation 2 is a complex operation that represents an

aggregate of removing and inserting operations. Replace() additional function is brought for ease. Deleting is considered in a start. The diagram has a form in t1 time (figure 2).



Figure 2. Deleting elements at diagram.

The chain including deleting element can be infinite size. Authors suggest the approach to perform deleting. If we meet element with timed label, then timed label is put in a stack. Next step an automaton follows about elements while not getting element with absent timed label. In this case it perform change_rel() special function that pop up from the stack timed label at deleting element and assign its with a current element. This algorithm is shown in figure 3. In order not to leave deleting elements suspended in a diagram when to pass deleting quasi-term delete() function perform that delete elements from the diagram. delete_with_link() function performs deleting elements with an enter link.

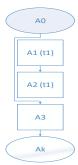


Figure 3. Assignment of links where deleting an element.

The grammar for that diagram is shown in table 5.

Table 5. Timed RVTI-grammar for UML AD.

Prev.	Quazi-term	Next	Operation
state		state	-
r_0	A0i	r_{I}	$insert()/W_3(k^{t(1)}==1)$
	A0	r_{I}	0
r_1	rel	r_2	0
r_2	Ai	r_{l}	$insert()/W_3(k^{t(1)} = = 1)$
	Ar	r_1	$replace()/W_3(k^{t(1)}==2)$
	Ad	r_3	$(delete(), W_1(l^{1m})) / W_3(k^{t(1)} = = 3)$
	Α	r_1	0
	Ak	r_5	0
r_3	drel	r_4	0
r_4	Ai	r_1	$(change_rel(), insert())/W_3(k^{t(1)} = = 1)$
	Ar	r_1	$(change_rel(), replace())/W_3(k^{t(1)}==2)$
	Ad	r_3	$delete_with_link()/W_3(k^{t(1)}==3)$
	Α	r_1	change_rel()
	Ak	r_5	change_rel()
r_5	no_label	r_k	*

6. Conclusion

The semantic features of hybrid dynamic design processes are analyzed in terms of their denotative and significative representations using the visual languages RC ASCON-Volga, BPMN and eEPC. The mathematical description of denotations and significative diagrammatically models of visual languages is given by authors, as well as the table description of denotations and significative

diagrammatically models of visual languages RC ASKON-Volga, BPMN and eEPC. The authors have expanded the list of semantic errors that occur in the workflow, four types of errors such as Synonym mismatch (denotative error), Discrepancy of antonyms (denotative error), Error conversionist relations (significative error), The inconsistency of the objects (significative error). Paradigms of the analysis and control of qualitative and quantitative characteristics of workflows are investigated. The author has developed automata-based temporal grammar for visual language RC ASKON-Volga, BPMN and UML AD, analysing and controlling these structural and semantic errors. The method of workflow transformation on the example of visual language UML AD is presented. In future works it is supposed to carry out researches of dynamic model of representation of processes of the automated systems on the basis of the temporal automatic grammar providing the mathematical description of hybrid dynamic design workflows for the analysis, control, transformation and interpretation that will allow to define the place of an error in diagram model.

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